# On a deformation diameter of Dynkin diagrams 

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Abstract. We introduce the notion of a deformation distance and calculate the diameter of Dynkin diagrams respect to this distance.

## Introduction

Through the paper, all graphs are finite, undirected and simple (i.e. without loops and multiple edges) with more than one vertices. The vertex and edges sets of a graph $G$ is denoted by $G_{0}$ and $G_{1}$, respectively. $\mathbb{R}^{+}$ denotes the set of positive real numbers.

By a vertex-weighted (respectively, edges-weighted) graph we mean a graph $G=\left(G_{0}, G_{1}\right)$ together with a weighted function $\varphi: G_{0} \rightarrow \mathbb{R}^{+}$ (respectively, $\varphi: G_{1} \rightarrow \mathbb{R}^{+}$); $\varphi(x)$ is called the weight of $x$.

If one talks on learning of metrics on graphs, the case of edges-weighted graphs is main. The $\varphi$-distance between vertices $u$ and $v$ of an edgesweighted graph, denoted $d_{\varphi}(u, v)$, is the weight $\sum_{i=1}^{s} \varphi\left(\lambda_{i}\right)$ of a shortest path $\lambda=\lambda_{1} \lambda_{2} \cdots \lambda_{s}$ between them.

Each vertex-weighted graph $G=\left(G_{0}, G_{1}, \varphi\right)$ we associate the edgesweighted graph $G^{+}=\left(G_{0}, G_{1}, \varphi^{+}\right)$, where, for any edge $\lambda$ between vertices $u$ and $v, \varphi^{+}(\lambda)=\varphi(u)+\varphi(v)$. In this paper we study the $\varphi^{+}$-distances on the Dynkin diagrams for $\varphi$ determined by the so-called $P$-limiting

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numbers of their vertices, which are connected with deformations of the corresponding quadratic Tits forms.

## 1. $P$-limiting numbers of Dynkin diagrams

Let $G$ be a Dynkin diagram and $s \in G_{0}$. The $s$-th $P$-limiting number of $G$ is the greatest number $a \in \mathbb{R}$ for which the quadratic form

$$
q_{G}^{(s)}(z, a)=q_{Q}\left(z_{1}, z_{2}, \ldots, z_{n}, a\right):=a z_{s}^{2}+\sum_{i \in G_{0} \backslash s} z_{i}^{2}-\sum_{\{i-j\} \in G_{1}} z_{i} z_{j}
$$

called the $s$-th deformation of the quadratic Tits form $q_{G}(z) \equiv q_{G}^{(s)}(z, 1)$, is not positive; in this connection, see [1,2]. The form $q_{G}^{(s)}(z, a)$ is called in [3] a point-local deformation of the form $q_{G}(z)$, and in this connection we denote the $s$-th $P$-limiting number by $\operatorname{pld}(s)$.

By [2, Theorem 5] the $P$-limiting numbers of the Dynkin diagrams $A_{n}, D_{n}, E_{6}, E_{7}, E_{8}$ are the following:



It is well-known that a (connected) graph $G$ is a Dynkin diagram iff its quadratic Tits form $q_{G}(z)$ is positive. So any graph $G$ with positive Tits form is associated the vertex weight pld. The corresponding edge weight $\operatorname{pld}^{+}$is determined by the following formula: $\operatorname{pld}^{+}(\lambda)=p l d(u)+p l d(v)$ for any edge $\lambda=u-v$ (see Introduction).

## 2. Calculation of diameters

We consider the Dynkin diagrams $G=A_{n}, D_{n}, E_{6}, E_{7}, E_{8}$ with the weight $p l d^{+}$(by the above assumption, $A_{1}$ is excluded). The diameter of $G$ (the maximum distance between two vertices) is denoted by $\mathcal{D}_{\text {pld }}{ }^{+}(G)$.

## Theorem 1.

$$
\mathcal{D}_{\operatorname{pld}^{+}}(G)=\left\{\begin{array}{cl}
\frac{2 n^{2}-n-1}{n}-2 \sum_{k=1}^{n-1} C_{n}^{k} \frac{(-1)^{k+1}}{k} & \text { for } G=A_{n} \\
\frac{4 n^{2}-7 n-4}{2 n}-\sum_{k=1}^{n-2} C_{n}^{k} \frac{(-1)^{k+1}}{k} & \text { for } G=D_{n}, \\
6 \frac{29}{60} & \text { for } G=E_{6}, \\
8 \frac{47}{60} & \text { for } G=E_{7} \\
11 \frac{37}{168} & \text { for } G=E_{8}
\end{array}\right.
$$

Proof. We write $d_{+}(i, j), \mathcal{D}_{+}(G)$ instead of $d_{\text {pld }^{+}}(i, j), \mathcal{D}_{\text {pld }^{+}}(G)$ and use that, for $i<j$,

$$
\begin{aligned}
d_{+}(i, j) & =2 \sum_{s=i}^{j} \operatorname{pld}^{+}(s)-\operatorname{pld}^{+}(i)-\operatorname{pld}^{+}(j) \\
& =2 \sum_{s=i}^{j-1} \operatorname{pld}^{+}(s)-\operatorname{pld}^{+}(i)+\operatorname{pld}^{+}(j)
\end{aligned}
$$

We let $H_{m}$ denote the $m$-th harmonic number:

$$
H_{m}=\sum_{k=1}^{m} C_{m}^{k} \frac{(-1)^{k+1}}{k}
$$

1) The case of $A_{n}$. Since

$$
\begin{aligned}
\sum_{i=1}^{n} \operatorname{pld}(i) & =\sum_{i=1}^{n}\left(1-\frac{n+1}{2 i(n+1-i)}\right) \\
& =n-\frac{1}{2}\left(\sum_{i=1}^{n} \frac{1}{i}+\sum_{i=1}^{n} \frac{1}{n+1-i}\right) \\
& =n-\frac{1}{2}\left(\sum_{i=1}^{n} \frac{1}{i}+\sum_{n+1-i=1}^{n} \frac{1}{n+1-i}\right)=n-H_{n}
\end{aligned}
$$

we have that

$$
\begin{aligned}
\mathcal{D}_{+}\left(A_{n}\right) & =d_{+}(1, n)=2 \sum_{i=1}^{n} \operatorname{pld}(i)-2\left(1-\frac{n+1}{2 n}\right) \\
& =2 n-2 H_{n}+\frac{1}{n}-1=2 n-2 H_{n-1}-\frac{1}{n}-1 \\
& =\frac{2 n^{2}-n-1}{n}-2 H_{n-1}
\end{aligned}
$$

2) The case of $D_{n}$. It is easy to see that $\mathcal{D}_{+}\left(D_{n}\right)=d_{+}(1, n-1)$. Since $\sum_{i=1}^{n-2} \operatorname{pld}(i)=n-2-\frac{1}{2} H_{n-2}$, we have that

$$
\begin{aligned}
\mathcal{D}_{+}\left(D_{n}\right) & =2 \sum_{i=1}^{n-2} \operatorname{pld}(i)-\frac{1}{2}+1-\frac{2}{n}=2 n-4-H_{n-2}+\frac{1}{2}-\frac{2}{n} \\
& =\frac{4 n^{2}-7 n-4}{2 n}-H_{n-2}
\end{aligned}
$$

3) The case of $E_{s}, s=6,7,8$. Simple direct calculations show that $d_{+}(1, s-1)>d_{+}(1, s), d_{+}(s-1, s)$ and the diameter $\mathcal{D}_{+}\left(E_{s}\right)=d_{+}(1, s-1)$ is equal to the number indicated in the formulation of the theorem.

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