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COUNTABLE HYPERBOLIC SYSTEMS IN THE THEORY OF NONLINEAR OSCILLATIONS

In this article a model example of a mixed problem for a fourth-order differential equation is reduced to initial-boundary value problem for countable hyperbolic system of first order coherent differential equations.

Key words and phrases: countable hyperbolic system, initial-boundary value problem.

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INTRODUCTION

Many problems from Elasticity Theory, Gas dynamics, Theory of plates and shells reduced to partial higher order differential equations [1, 2, 3] using Fourier method [3] or the method of Principal coordinates [1]. As a result we get a infinite system of ordinary differential equations. The Theory of countable ordinary differential systems is described in the monograph [4]. However, in many cases, particularly in the famous Hadamard's example [5, p.112] about correct solvability of initial problem for Cauchy-Riemann equation, if interpret partial solutions like $u_n = I_n(t) \cos nx$, $v_n = J_n(t) \sin nx$, we get a countable system of partial first order differential equations. Similar systems occur in determining of the generalized solution for hyperbolic first order equations [5, p.132], in the investigation of mathematical models of selfexcited oscillator with distributed parameters [6], in many periodic solutions of quasi-linear hyperbolic systems [7] and others. Some questions about the correct solvability of initialboundary value problems for countable hyperbolic systems of first order differential equations are considered in [8, 9, 10, 13].

1 STATEMENT OF PROBLEM

In the domain $Q = \{(t, x, y) : t \in (0, T), x \in (0, l_1), y \in (0, l_2)\}$ we consider fourth order partial differential equation

$$u_{tt} + B(t, x)(u_{tx} + u_{xyy}) + C(t, x)u_{xx} + u_{yyyy} + 2u_{tyy} = f(t, x, y, u, u_t, u_x, u_{yy})$$
(1)

with initial

$$u|_{t=0} = \varphi(x, y),$$

$$u_t|_{t=0} = \psi(x, y), \quad 0 \le x \le l_1, \ 0 \le y \le l_2,$$
(2)

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and boundary conditions

$$\begin{aligned} u|_{y=0} &= u|_{y=l_2} = 0, \\ \frac{\partial^2 u}{\partial y^2}\Big|_{y=0} &= \frac{\partial^2 u}{\partial y^2}\Big|_{y=l_2} = 0, \quad 0 \le x \le l_1, \ 0 \le t \le T, \\ u|_{x=0} &= \mu(t,y), \ u|_{x=l_1} = \nu(t,y), \quad 0 \le y \le l_2, \ 0 \le t \le T, \end{aligned}$$
(3)

where

$$\begin{split} \mu(0,y) &= \varphi(0,y), \quad \nu(0,y) = \varphi(l_1,y), \quad \mu'_t(0,y) = \psi(0,y), \quad \nu'_t(0,y) = \psi(l_1,y), \\ \varphi(x,0) &= \varphi(x,l_2) = 0, \quad \psi(x,0) = \psi(x,l_2) = 0, \\ \varphi''_{yy}(x,0) &= \varphi''_{yy}(x,l_2) = 0, \quad \psi''_{yy}(x,0) = \psi''_{yy}(x,l_2) = 0. \end{split}$$

2 The reduction equation (1) to a countable system of second order DIFFERENTIAL EQUATIONS

We will search solution of the problem (1)–(3) using separation of variables method, namely in the form of a series

$$u(t, x, y) = v_0(t, x) + \sum_{n=1}^{\infty} \left(v_n(t, x) \cos \alpha_n y + w_n(t, x) \sin \alpha_n y \right),$$
(4)

where $\alpha_n = \frac{2\pi n}{l_2}$ (see [12, 13]). Substituting (4) in boundary conditions (3), we obtain $\sum_{n=0}^{\infty} v_n(t,x) = 0$ and $\sum_{n=1}^{\infty} \alpha_n^2 v_n(t,x) = 0$. Suppose, that $v_n(t,x) \equiv 0$ for all $n \in \mathbb{N}$ and $(t,x) \in \Pi^{t,x} = (0,T) \times (0,l_1)$.

Assume that the initial data of the problem (1)–(3) are sufficiently smooth. Let compatibility conditions are fulfilled and the initial data are unambiguous decomposed in a series

$$f\left(t, x, y, u, \frac{\partial u}{\partial t}, \frac{\partial u}{\partial x}, \frac{\partial^2 u}{\partial y^2}\right) = \sum_{n=1}^{\infty} f_n\left(t, x, w_1, w_2, \dots, \frac{\partial w_1}{\partial t}, \frac{\partial w_2}{\partial t}, \dots, \frac{\partial w_1}{\partial x}, \frac{\partial w_2}{\partial x}, \dots\right) \sin \alpha_n y, \quad (5)$$

$$\varphi(x,y) = \sum_{n=1}^{\infty} \varphi_n(x) \sin \alpha_n y, \quad \psi(x,y) = \sum_{n=1}^{\infty} \psi_n(x) \sin \alpha_n y, \quad (6)$$

$$\mu(t,y) = \sum_{n=1}^{\infty} \mu_n(t) \sin \alpha_n y, \quad \nu(t,y) = \sum_{n=1}^{\infty} \nu_n(t) \sin \alpha_n y.$$
(7)

Let $\omega_n = \left(\frac{2\pi n}{l_2}\right)^2$. Substitute equality (4) in equation (1) and conditions (2) and (3). After multiplying received equalities by $\sin \alpha_m y$, (m = 1, 2, ...) and integrating in the interval from 0 to l_2 , with considering conditions (5)–(7), we obtain the countable system of second-order differential equations

$$\frac{\partial^2 w_n}{\partial t^2} + B(t,x) \left(\frac{\partial^2 w_n}{\partial t \partial x} - \omega_n \frac{\partial w_n}{\partial x} \right) + C(t,x) \frac{\partial^2 w_n}{\partial x^2} + \omega_n^2 w_n - 2\omega_n \frac{\partial w_n}{\partial t} = f_n \left(t, x, w_1, w_2, \dots, \frac{\partial w_1}{\partial t}, \frac{\partial w_2}{\partial t}, \dots, \frac{\partial w_1}{\partial x}, \frac{\partial w_2}{\partial x}, \dots \right), \quad n \in \mathbb{N},$$
(8)

with initial and boundary conditions

$$w_n|_{t=0} = \varphi_n(x), \left. \frac{\partial w_n}{\partial t} \right|_{t=0} = \psi_n(x), \quad 0 \le x \le l_1,$$

$$w_n|_{x=0} = \mu_n(t), \ w_n|_{x=l_1} = \nu_n(t), \quad 0 \le t \le T.$$

Propose a change of variables $w_n = v_n e^{\omega_n t}$. Then all derivatives will be rewritten in a form

$$\frac{\partial w_n}{\partial t} = \left(\frac{\partial v_n}{\partial t} + \omega_n v_n\right) e^{\omega_n t}, \quad \frac{\partial w_n}{\partial x} = \frac{\partial v_n}{\partial x} e^{\omega_n t},$$
$$\frac{\partial^2 w_n}{\partial t^2} = \left(\frac{\partial^2 v_n}{\partial t^2} + 2\omega_n \frac{\partial v_n}{\partial t} + \omega_n^2 v_n\right) e^{\omega_n t},$$
$$\frac{\partial^2 w_n}{\partial t \partial x} = \left(\frac{\partial^2 v_n}{\partial t \partial x} + \omega_n \frac{\partial v_n}{\partial x}\right) e^{\omega_n t}, \quad \frac{\partial^2 w_n}{\partial x^2} = \frac{\partial^2 v_n}{\partial x^2} e^{\omega_n t}.$$

As a result, we obtain the countable system of second order differential equations

$$\frac{\partial^2 v_n}{\partial t^2} + B(t, x) \frac{\partial^2 v_n}{\partial t \partial x} + C(t, x) \frac{\partial^2 v_n}{\partial x^2} = \tilde{f}_n \Big(t, x, v_1, v_2, \dots, \frac{\partial v_1}{\partial t}, \frac{\partial v_2}{\partial t}, \dots, \frac{\partial v_1}{\partial x}, \frac{\partial v_2}{\partial x}, \dots \Big), \quad n \in \mathbb{N},$$

where

$$\tilde{f}_n = e^{-\omega_n t} f_n \Big(t, x, v_1 e^{\omega_n t}, v_2 e^{\omega_n t}, \dots, \\ \frac{\partial v_1}{\partial t} e^{\omega_n t} + \omega_n v_1 e^{\omega_n t}, \frac{\partial v_2}{\partial t} e^{\omega_n t} + \omega_n v_2 e^{\omega_n t}, \dots, \frac{\partial v_1}{\partial x} e^{\omega_n t}, \frac{\partial v_2}{\partial x} e^{\omega_n t}, \dots \Big).$$

Initial and boundary conditions will be rewritten in a form

$$\begin{aligned} v_n|_{t=0} &= \varphi_n(x), \quad \frac{\partial v_n}{\partial t}\Big|_{t=0} = \tilde{\psi}_n(x), \qquad 0 \le x \le l_1, \\ v_n|_{x=0} &= \tilde{\mu}_n(t), \quad v_n|_{x=l_1} = \tilde{v}_n(t), \qquad 0 \le t \le T, \end{aligned}$$

where $\tilde{\mu}_n(t) = \mu_n(t)e^{-\omega_n t}, \tilde{v}_n(t) = v_n(t)e^{-\omega_n t}, \tilde{\psi}_n(x) = \psi_n(x) - \omega_n \varphi_n(x). \end{aligned}$

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3 The reduction to countable system of first order differential equations

Suppose that $\Delta(t, x) = B^2(t, x) - 4C(t, x) > 0$, for all $(t, x) \in \Pi^{t,x}$, so each equation of the system (8) has hyperbolic type. We denote

$$\lambda_i(t, x) = \frac{B(t, x) + (-1)^i \sqrt{\Delta(t, x)}}{2},$$
$$v_{i,n} = \frac{\partial v_n}{\partial t} + \lambda_i \frac{\partial v_n}{\partial x}, \quad i = 1, 2.$$

Then

$$\frac{\partial v_n}{\partial x} = \frac{v_{2,n} - v_{1,n}}{\sqrt{\Delta}},\\ \frac{\partial v_n}{\partial t} = v_{2,n} - (B + \sqrt{\Delta}) \frac{v_{2,n} - v_{1,n}}{2\sqrt{\Delta}}.$$

Due to variables changes, each equation of the system (8) would be equivalent to the system of equations [5, 11]

$$\frac{\partial v_{i,n}}{\partial t} + \lambda_{3-i} \frac{\partial v_{i,n}}{\partial x} = \frac{1}{\sqrt{\Delta}} \left(\frac{\partial \lambda_i}{\partial t} + \lambda_{3-i} \frac{\partial \lambda_i}{\partial x} \right) (v_{2,n} - v_{1,n}) \\
+ \tilde{f}_n \left(t, x, v_1, \dots, v_{2,1} - (B + \sqrt{\Delta}) \frac{v_{2,1} - v_{1,1}}{2\sqrt{\Delta}}, \dots, \frac{v_{2,1} - v_{1,1}}{\sqrt{\Delta}}, \dots \right),$$
(9)
$$\frac{\partial v_n}{\partial t} = v_{2,n} - (B + \sqrt{\Delta}) \frac{v_{2,n} - v_{1,n}}{2\sqrt{\Delta}}, \quad i = 1, 2, \quad n \in \mathbb{N}.$$

Suppose, that $\lambda_1(t, x) \ge 0$, $\lambda_2(t, x) \le 0$ (a sufficient condition is execution the inequality $|B(t, x)| \le \sqrt{\Delta(t, x)}$). Conduct characteristic $L_1(0, 0)$ through the point (0, 0) and characteristic $L_2(0, l_1)$ through the point $(0, l_1)$, which are the solutions of Cauchy problems

$$\frac{dx}{dt} = \lambda_1(t, x), \ x(0) = 0, \ \frac{dx}{dt} = \lambda_2(t, x), \ x(0) = l_1.$$

Thus, rectangle $\Pi^{t,x}$ is divided into three parts (see Figure 1).



Figure 1: Partition of domain by characteristics with slope $\lambda_1 \ge 0$, $\lambda_2 \le 0$.

In subdomain Π_0 for system (9) define the initial conditions

$$v_n|_{t=0} = \varphi_n(x), v_{i,n}|_{t=0} = \tilde{\psi}_n(x) + \lambda_i|_{t=0} \frac{d\varphi_n}{dx}(x), \quad i = 1, 2.$$

In Π_1 for v_n and $v_{2,n}$ define the initial conditions, and for $v_{1,n}$ define the boundary conditions on the left side

$$\begin{aligned} v_n|_{t=0} &= \varphi_n(x), \quad v_{2,n}|_{t=0} = \tilde{\psi}_n(x) + \lambda_2|_{t=0} \frac{d\varphi_n}{dx}(x), \\ v_{1,n}|_{x=0} &= \frac{2\sqrt{\Delta}}{B+\sqrt{\Delta}} \Big|_{x=0} \frac{d\tilde{\mu}_n}{dt}(t) + \Big(1 - \frac{2\sqrt{\Delta}}{B+\sqrt{\Delta}}\Big)\Big|_{x=0} v_{2,n}|_{x=0}. \end{aligned}$$

In subdomain Π_2 for v_n and $v_{1,n}$ define the initial conditions, and for $v_{2,n}$ define the boundary conditions on the right side

$$\begin{aligned} v_n|_{t=0} &= \varphi_n(x), \quad v_{1,n}|_{t=0} = \tilde{\psi}_n(x) + \lambda_1|_{t=0} \frac{d\varphi_n}{dx}(x), \\ v_{2,n}|_{x=l_1} &= \frac{2\sqrt{\Delta}}{\sqrt{\Delta} - B}\Big|_{x=l_1} \frac{d\tilde{\mu}_n}{dt}(t) + \frac{B + \sqrt{\Delta}}{B - \sqrt{\Delta}}\Big|_{x=l_1} v_{1,n}|_{x=l_1}. \end{aligned}$$

Remark 3.1. If the following condition is not fulfilled $\lambda_1 \ge 0, \lambda_2 \le 0$, there is possible to get such cases:

i) $\lambda_1 \ge \lambda_2 \ge 0$, $\lambda_1^2 + \lambda_2^2 \ne 0$; *ii*) $\lambda_1 \le \lambda_2 \le 0$, $\lambda_2^2 + \lambda_2^2 \ne 0$

ii) $\lambda_1 \leq \lambda_2 \leq 0$, $\overline{\lambda_1^2} + \overline{\lambda_2^2} \neq 0$.

In the first case, for system (1) it is necessary to define the boundary conditions in the next form

$$u|_{x=0} = \mu(t,y), u_x|_{x=0} = \nu(t,y), \quad 0 \le y \le l_2, \ 0 \le t \le T.$$



tics with slope $\lambda_1, \lambda_2 > 0$.

Figure 2: Partition of domain by characteris- Figure 3: Partition of domain by characteristics with slope $\lambda_1, \lambda_2 < 0$.

Conduct characteristics $L_1(0,0)$ and $L_2(0,0)$ through the point (0,0), which are the solutions of Cauchy problems

$$\frac{dx}{dt} = \lambda_i, \ x(0) = 0, \quad i = 1, 2.$$

Thus, rectangle $\Pi^{t,x}$ is devided into three parts (see Figure 2). In subdomain Π_0 define the initial conditions

$$v_n|_{t=0} = \varphi_n(x), \ v_{i,n}|_{t=0} = \tilde{\psi}_n(x) + \lambda_i|_{t=0} \frac{d\varphi_n}{dx}(x), \quad i = 1, 2.$$

In Π_1 for v_n and $v_{2,n}$ define the initial conditions, and for $v_{1,n}$ define the boundary conditions on the left side

$$v_n|_{t=0} = \varphi_n(x), \quad v_{2,n}|_{t=0} = \tilde{\psi}_n(x) + \lambda_2|_{t=0} \frac{d\varphi_n}{dx}(x),$$
$$v_{1,n}|_{x=0} = \frac{d\tilde{\mu}_n}{dt}(t) + \lambda_1|_{x=0}\tilde{\nu}_n(t).$$

In subdomain Π_2 for v_n define the initial conditions, and for $v_{1,n}$ and $v_{2,n}$ define the boundary conditions on the left side

$$v_n|_{t=0} = \varphi_n(x), \quad v_{i,n}|_{x=0} = \frac{d\tilde{\mu}_n}{dt}(t) + \lambda_i|_{x=0}v_n(t).$$

Similarly, the initial and boundary conditions would be defined in case, when $\lambda_1 \leq \lambda_2 \leq 0$, $\lambda_1^2 + \lambda_2^2 > 0$ (see Figure 3). In this case for the system (1) we have to set the boundary conditions in the following form

$$u|_{x=l_1} = \mu(t,y), \ u_x|_{x=l_1} = \nu(t,y), \quad 0 \le y \le l_2, \ 0 \le t \le T.$$

EXAMPLE 4

For example, consider a differential equation

$$u_{tt} - x^2 u_{xx} + u_{yyyy} + 2u_{tyy} = -xu_x + \left(-\frac{\pi}{6} + \pi y - y^2\right)u + f(t, x, y), \tag{10}$$

where f(t, x, y) — some polynomial of (t, x, y), with initial conditions

$$u|_{t=0} = 0, \ u_t|_{t=0} = \left(y^5 - \frac{5}{2}\pi y^4 + \frac{5}{3}\pi^2 y^3 - \frac{1}{6}\pi^4 y\right)(\pi x - x^2), \quad 0 \le x \le \pi, \ 0 \le y \le \pi,$$

and homogeneous boundary conditions

$$\frac{\partial^2 u}{\partial y^2}\Big|_{y=0} = \frac{\partial^2 u}{\partial y^2}\Big|_{y=\pi} = 0,$$

$$u|_{y=0} = u|_{y=\pi} = 0, \ u|_{x=0} = u|_{x=\pi} = 0, \quad 0 \le x \le \pi, \ 0 \le y \le \pi, \ 0 \le t \le T.$$
(11)

The solution can be sought in the form $u(t, x, y) = \sum_{n=1}^{\infty} w_n(t, x) \sin 2ny$. Functions on the right side of the equation and the initial conditions decomposed in such series

$$y^{5} - \frac{5}{2}\pi y^{4} + \frac{5}{3}\pi^{2}y^{3} - \frac{1}{6}\pi^{4}y = -\sum_{n=1}^{\infty} \frac{15}{2n^{5}}\sin 2ny,$$

$$f(t, x, y) = \sum_{n=1}^{\infty} f_{n}(t, x)\sin 2ny,$$

$$-\frac{\pi^{2}}{6} + \pi y - y^{2} = -\sum_{m=1}^{\infty} \frac{1}{m^{2}}\cos 2my,$$

$$\left(-\frac{\pi^{2}}{6} + \pi y - y^{2}\right)u = \sum_{n=1}^{\infty} \sum_{k=1}^{\infty} \sum_{m=1}^{\infty} \frac{w_{k}}{m^{2}}\delta_{n}^{k,m}\sin 2ny,$$

where $\delta_n^{k,m} = \begin{cases} \frac{1}{2}, & \text{if } k + m - n = 0, \\ -\frac{1}{2}, & \text{if } (k - m + n)(m - k + n) = 0. \end{cases}$ So, we obtain the countable system of second order differential equations

$$\frac{\partial^2 w_n}{\partial t^2} - x^2 \frac{\partial^2 w_n}{\partial x^2} + \omega_n^2 w_n - 2\omega_n \frac{\partial w_n}{\partial t} = -x \frac{\partial w_n}{\partial x} + \sum_{k=1}^{\infty} \sum_{m=1}^{\infty} \frac{w_k}{m^2} \delta_n^{k,m} + f_n, \quad n \in \mathbb{N},$$
(12)

with initial conditions

$$w_n|_{t=0}=0, \quad rac{\partial w_n}{\partial t}\Big|_{t=0}=-rac{15}{2n^5}(\pi x-x^2), \qquad 0\leq x\leq \pi, \ n\in\mathbb{N},$$

and homogeneous boundary conditions.

Perform a change of variables $w_n = v_n e^{\omega_n t}$. The system (12) will be rewritten in a form

$$\frac{\partial^2 v_n}{\partial t^2} - x^2 \frac{\partial^2 v_n}{\partial x^2} + x \frac{\partial v_n}{\partial x} = \sum_{k=1}^{\infty} \sum_{m=1}^{\infty} \frac{v_k e^{(\omega_k - \omega_n)t}}{m^2} \delta_n^{k,m} + \frac{f_n}{e^{\omega_n t}}, \quad n \in \mathbb{N},$$

with initial and homogeneous boundary conditions

$$v_n|_{t=0} = 0, \quad \frac{\partial v_n}{\partial t}\Big|_{t=0} = -\frac{15}{2n^5}(\pi x - x^2), \qquad 0 \le x \le \pi, \ n \in \mathbb{N}.$$

In this case $\Delta = 4x^2$, that is

$$v_{1,n} = rac{\partial v_n}{\partial t} + x rac{\partial v_n}{\partial x}, \ v_{2,n} = rac{\partial v_n}{\partial t} - x rac{\partial v_n}{\partial x}.$$

As a result, we obtain the countable system of first order differential equations

$$\begin{cases} \frac{\partial v_{1,n}}{\partial t} - x \frac{\partial v_{1,n}}{\partial x} = \sum_{k=1}^{\infty} \sum_{m=1}^{\infty} \frac{v_k e^{(\omega_k - \omega_n)t}}{m^2} \delta_n^{k,m} + \frac{f_n}{e^{\omega_n t}}, \\ \frac{\partial v_{2,n}}{\partial t} + x \frac{\partial v_{2,n}}{\partial x} = \sum_{k=1}^{\infty} \sum_{m=1}^{\infty} \frac{v_k e^{(\omega_k - \omega_n)t}}{m^2} \delta_n^{k,m} + \frac{f_n}{e^{\omega_n t}}, \\ \frac{\partial v_n}{\partial t} = \frac{v_{1,n} + v_{2,n}}{2}. \end{cases}$$
(13)

Since $\lambda_1 = x > 0$, $\lambda_2 = -x < 0$, initial and boundary conditions will be rewritten in a form:

$$v_n|_{t=0} = 0, \ v_{1,n}|_{t=0} = -\frac{15}{2n^5} (\pi x - x^2), \ v_{2,n}|_{t=0} = -\frac{15}{2n^5} (\pi x - x^2), \ \ (t,x) \in \Pi_0;$$
 (14)

$$v_n|_{t=0} = 0, \ v_{2,n}|_{t=0} = -\frac{15}{2n^5} (\pi x - x^2), \ v_{1,n}|_{x=0} = -v_{2,n}|_{x=0}, \quad (t,x) \in \Pi_1;$$
 (15)

$$v_n|_{t=0} = 0, \ v_{1,n}|_{t=0} = -\frac{15}{2n^5} (\pi x - x^2), \ v_{2,n}|_{x=\pi} = -v_{1,n}|_{x=\pi}, \quad (t,x) \in \Pi_2.$$
 (16)

After solving the problem (13)–(16) (see [9]), we will obtain a system of functions

$$v_n = -\frac{15t}{2n^5 e^{\omega_n t}} (\pi x - x^2),$$

$$v_{1,n} = -\frac{15t}{2n^5 e^{\omega_n t}} ((1 - \omega_n t)(\pi x - x^2) + t(\pi x - 2x^2)),$$

$$v_{2,n} = -\frac{15t}{2n^5 e^{\omega_n t}} ((1 - \omega_n t)(\pi x - x^2) - t(\pi x - 2x^2)).$$

So $w_n = \frac{-15t}{2n^5}(\pi x - x^2).$

Therefore $u(t, x, y) = \frac{15t}{2}(x^2 - \pi x) \sum_{n=1}^{\infty} \frac{\sin 2ny}{n^5}$ is the exact solution of the problem (10)–(11). In the Figure 4 we can see 3D-graphics of the solution in the case of t = 0.25 and t = 0.5.



Figure 4: Graphics of solutions at t = 0.25 and t = 0.5.

Together with the problem (13)–(16), we consider truncated system

$$\begin{cases} \frac{\partial v_{1,n}}{\partial t} - x \frac{\partial v_{1,n}}{\partial x} = \sum_{k=1}^{N} \sum_{m=1}^{\infty} \frac{v_k e^{(\omega_k - \omega_n)t}}{m^2} \delta_n^{k,m} + \frac{f_n}{e^{\omega_n t}}, \\ \frac{\partial v_{2,n}}{\partial t} + x \frac{\partial v_{2,n}}{\partial x} = \sum_{k=1}^{N} \sum_{m=1}^{\infty} \frac{v_k e^{(\omega_k - \omega_n)t}}{m^2} \delta_n^{k,m} + \frac{f_n}{e^{\omega_n t}}, \\ \frac{\partial v_n}{\partial t} = \frac{v_{1,n} + v_{2,n}}{2}, \end{cases}$$
(17)

with the initial and the boundary conditions (14)–(16). With some suppositions [10], the solutions of the problems (17), (14)–(16) and (13)–(16) will be as close as possible.

Let v_n^N is the solution of the problem (17), (14)–(16) and $u^N(t, x, y) = \sum_{n=1}^N w_n^N \sin 2ny$. Figure 5 shows a graph of $\frac{\max_{t,x,y} \{|u^N(t,x,y)-u(t,x,y)|\}}{\max_{t,x,y} \{|u(t,x,y)|\}}$.



Figure 5: Dependence of difference between exact and approximate solution by *N*.

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У цій роботі на модельному прикладі мішаної задачі для диференціального рівняння четвертого порядку показано, як таку задачу можа звести до задачі для зліченної гіперболічної системи зв'язних рівнянь першого порядку.

Ключові слова і фрази: зліченна гіперболічна система, мішана задача.