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PROBABILITY MODEL FOR THE ERROR ESTIMATION AT SEISMIC-ACOUSTIC FORECAST WHILE COAL MINING

Seismic-acoustic method is widely used currently to predict rock bursts and outbursts in coal mines. To improve this method the two prognostic criteria model is developed to avoid the forecast errors. The proposed mathematical model provides decreasing the probability of type I errors ("false positive") without significant growth of type II errors ("false negative"). The probabilistic model proposed takes into consideration a time parameter as well.

Keywords: probability model; seismic-acoustic method; outburst forecast.

На даний час широко застосовується сейсмоакустичний метод для прогнозування гірських ударів і викидів гірських порід у вугільних шахтах. Для вдосконалення цього методу розроблено модель з двома прогностичними критеріями, щоб уникнути помилок прогнозу. Запропонована математична модель передбачає зменшення ймовірності помилок I роду ("помилково позитивних") без істотного зростання помилок II роду ("помилково негативних") та враховує часовий параметр.

Ключові слова: ймовірнісна модель; сейсмоакустичний метод; прогноз викидів.

Formulation of the problem

The study of gas-dynamic phenomena mechanism in mines [1] is one of the key tasks associated with the coal and gas outburst prediction.

Seismic-acoustic method is widely used currently to predict the rock bursts and outbursts in coal mines. Nevertheless, the average level of the method reliability is 60—70 % [2]. The probability of type II errors ("false negative") at predicting is about 3 % [3]. But the availability of type I errors ("false positive") can be significant [5]. The probability of such error occurrence should be decreased, but at the same time increasing the type II errors ("false negative") must be excluded.

Analysis of recent investigations and publications

The outburst forecast at coal mining based on acoustic signals involves a hazard index developed in [5]:

$$K_{\theta} = \frac{A_{\theta}}{A_H},$$

where A_{θ} is an amplitude of high-frequency component in acoustic signal spectrum recorded in the rock mass while mining operations, A_H is an amplitude of the low-frequency component in this spectrum. To improve the forecast technics the prognostic model has been developed by involving additional index [6]:

$$K_S = \frac{S_{\theta}}{S},$$

where S_{θ} is the spectrum area corresponding to the high-frequency component, S is a general area of the amplitude-frequency spectrum. Values S_{θ} and S can be determined by spectral estimation of signals generated by rock-destruction mechanisms:

$$S = \Delta g \cdot \sum_{i=0}^{i \max} A_i, \quad S_B = \Delta g \cdot \sum_{i:700 < g < 1250} A_i,$$

where $A_i, i = 0, i \max$ are the amplitude magnitude, Δg is the frequency step of the considered spectrum area. The amplitude spectrum can be estimated by the fast Fourier transformation [10].

The critical value of the prognostic index K_g should be determined and adjusted in accordance with the appendix P.8 [4] individually for different types of excavations. The critical value of the prognostic index K_S alters obviously within the range [0, 1] and should be estimated based on practical observations.

Respectively the criteria should be held to identify the hazard situation:

$$K_g = \frac{A_g}{A_H} \geq K_g^* \quad (1)$$

for some interval of time Δt and

$$K_S = \frac{S}{S} \geq K_S^*, \quad (2)$$

where K_g^* is the critical value of the prognostic index K_g , K_S^* is the critical value of the prognostic index K_S . The criterion (2) proposed in [6] is based on studying the crack initiation under the harmonic and static stress components [7, 8].

The probability of type I errors ("false positive") according to the criterion (1) alters in the range from 5 % to 47 % [5]. That is why this criterion requires some varies to decrease the probability of these errors. That is why the new model has been developed [6] for simultaneous applying both outburst hazard criteria to improve the gas-dynamic phenomena prediction. To prove the effectiveness of the proposed model the probability of forecast errors should be estimated.

Formulation of the research objective

An algorithm should be developed using prognostic indices K_g, K_S to improve the seismic-acoustic method for predicting gas-dynamic phenomena in mines. That is why the proposed model in [6] should be corrected to decrease the probability of type I errors ("false positive") without increasing probability of type II errors ("false negative").

Statement of the main material

Estimating the probability of an error occurring at the outburst forecast based on acoustic signals.

While coal mining the special seismic bureau must give message «hazardous», if the criterion (1) is fulfilled during the time interval Δt and over.

The criterion (1) can be corrected by increasing the critical value K_g^* and/or by increasing the time interval Δt . These alters provide decreasing the probability of the type I errors («false positive»). But at the same time such varies obviously increase the probability of the type II errors («false negative») representing greatest hazard.

Physical interpretation of the criterion (1) is following. Gas-dynamic phenomena are associated with crack initiation identified by growing of high-frequency component of the spectrum A_g [5]. Hence, increasing of the value A_g means increasing the ratio (1). However, the prognostic indicator K_g can grow as well if its denominator decreases. But decreasing of low-frequency component of the spectrum A_H does not mean dangerous situation in rock mass [10] and does not identifies gas-dynamic onset.

This fact can be substantial reason for the type I errors («false positive») while applying the criterion (1). The criterion (2) has not this flaw because depends on the amplitude spectrum integral. The physical interpretation of the prognostic index K_S is the ratio of the high-frequency oscillations power to the total oscillations power at given «point» of the study.

As mentioned above the two-criteria outburst model that included prognostic indicators K_e and K_S has been developed [6]. But the model fetches have not been founded and the introduction of a time parameter has not been done. That is why this paper focused on developing the probability models of occurring both type errors («false positive» and «false negative») while acoustic analysis.

To identify different level of hazard we introduce two notions:

- possible hazardous rock state/possible not hazardous rock state,
- hazardous rock state/not hazardous rock state.

First notion means fulfillment/non-fulfillment of criteria (1) and (2), second notion means making decision based on the observations over a time period ΔT .

Additionally, following notations should be involved:

$H_0 = \{\text{not hazardous rock state}\}$ is a primary hypothesis;

$\overline{H_0} = \{\text{hazardous rock state}\}$ is an alternative hypothesis.

Such events should be discussed:

$A_i = \{\text{the signal is «possible not hazardous rock state» according to the } i\text{-th criterion}\};$

$\overline{A_i} = \{\text{the signal is «possible hazardous rock state» according to the } i\text{-th criterion}\};$

$B = \{\text{decision «not hazardous rock state»}\};$

$\overline{B} = \{\text{decision «hazardous rock state»}\};$

$H_0 A_i = \{\text{type I errors according to the } i\text{-th criterion («false positive»}\};$

$\overline{H_0 A_i} = \{\text{type II errors according to the } i\text{-th criterion («false negative»}\};$

$H_0 \overline{B} = \{\text{decision has a type I error}\};$

$\overline{H_0 B} = \{\text{decision has a type II error}\}.$

$\alpha_i = P_{H_0}(\overline{A_i})$ is type I error probability according to the i -th criterion;

$\beta_i = P_{\overline{H_0}}(A_i)$ is type II error probability according to the i -th criterion;

$\alpha = P_{H_0}(\overline{B})$ is type I error probability of made decision;

$\beta = P_{\overline{H_0}}(B)$ is type II error probability of made decision.

The type I and II errors probabilities are determined by the criterion function:

$$B = f(\varphi_1, \varphi_2),$$

where φ_1 is a function with respect of prognostic indicator K_e , φ_2 is a function with respect of prognostic indicator K_S .

Consider two possible variants for the decision making. First variant is following. Let the criterion function be

$$B = A_1 A_2. \quad (3)$$

In this case we make a decision «not hazardous rock state» when both criteria show the prediction «possible not hazardous rock state». Then opposite event looks like $\overline{B} = \overline{A_1 A_2} = \overline{A_1} + \overline{A_2}$. The type I errors probability of making decision can be estimated in such way:

$$\begin{aligned} \alpha &= P_{H_0}(\overline{B}) = P_{H_0}(\overline{A_1} + \overline{A_2}) = P_{H_0}(\overline{A_1}) + P_{H_0}(\overline{A_2}) - P_{H_0}(\overline{A_1})P_{H_0|\overline{A_1}}(\overline{A_2}) = \\ &= \alpha_1 + \alpha_2 - \alpha_1\alpha_{2(1)} = \alpha_1 + \alpha_2 \cdot \left(1 - \alpha_{2(1)} \cdot \frac{\alpha_1}{\alpha_2}\right) \end{aligned} \quad (4)$$

and the type II errors probability looks like:

$$\beta = P_{\overline{H_0}}(B) = P_{\overline{H_0}}(A_1 A_2) = P_{\overline{H_0}}(A_1)P_{\overline{H_0}|A_1}(A_2) = \beta_1\beta_{2(1)}, \quad (5)$$

where $\alpha_{2(1)}$ and $\beta_{2(1)}$ are the type I and II errors probabilities according to the criterion (2) respectively under condition that the type I errors also has occurred according to the criterion (1).

If the errors are independent according to different criteria, then $\alpha_{2(1)} = \alpha_2$ and $\beta_{2(1)} = \beta_2$. However, this situation should be considered as extreme one because the obvious dependence between events A_1 and A_2 exists. That is why we suppose the probabilities satisfy the inequality $\alpha_{2(1)} > \alpha_2$ and $\beta_{2(1)} > \beta_2$.

It can be seen from the expression (4) that the type I error («false positive») probability increases, but at the same time the type II error («false negative») probability decreases according to the expression (5). The result obtained goes against the constitutive idea of the model that aims decreasing the type I errors probability in the hazard forecast.

Consider second possible variant for the decision making. Let the criterion function be

$$B = A_1 + A_2. \quad (6)$$

In this case we decide «not hazardous rock state» when at least one of the criteria shows the prediction «possible not hazardous rock state».

Then opposite event is $\overline{B} = \overline{A_1 + A_2} = \overline{A_1} \overline{A_2}$ and

$$\alpha = P_{H_0}(\overline{B}) = P_{H_0}(\overline{A_1} \overline{A_2}) = P_{H_0}(\overline{A_1}) \cdot P_{H_0|\overline{A_1}}(\overline{A_2}) = \alpha_1 \cdot \alpha_{2(1)}, \quad (7)$$

$$\begin{aligned} \beta &= P_{\overline{H_0}}(B) = P_{\overline{H_0}}(A_1 + A_2) = P_{\overline{H_0}}(A_1) + P_{\overline{H_0}}(A_2) - P_{\overline{H_0}}(A_1)P_{\overline{H_0}|A_1}(A_2) = \\ &= \beta_1 + \beta_2 - \beta_1 \cdot \beta_{2(1)} = \beta_1 + \beta_2 \cdot \left(1 - \beta_{2(1)} \cdot \frac{\beta_1}{\beta_2}\right). \end{aligned} \quad (8)$$

Obviously, the type I error («false positive») probability decreases according to the equation (7). At the same time the type II error («false negative») probability increases according to the equation (8) because of summarizing quantities β_1, β_2 . However according to experimental data [5] the probabilities $\beta_1, \beta_2, \beta_{2(1)}$ are sufficiently small. That is why the type II error probability growth in the equation (8) is not significant. Obtained result provides decreasing the type I error probability in hazard forecast.

Thus, the variant of decision making according the model (6) meets the requirements of prediction «not hazardous rock state».

It should be noted that making decision «not hazardous rock state» according to the criterion (2) is not sufficiently confirmed experimentally. That is why it should be entered a twice time interval in criterion (1) to check the criterion (2) fulfillment. As a result the prediction «not hazardous rock state» looks like:

$$(A_1 + A_2) \Big|_{t \in [t_0, t_0 + \Delta T]} \cdot A_1 \Big|_{t \in [t_1, t_1 + 2 \cdot \Delta T]}, \quad (9)$$

where t_0, t_1 are arbitrary time moments in the interval investigated.

Then the prediction «not hazardous rock state» according to the developed model (9) can be represented:

$$\left[(K_B < K_B^*) + (K_S < K_S^*) \right]_{t \in [t_0, t_0 + \Delta T]} \cdot (K_B < K_B^*)_{t \in [t_1, t_1 + 2 \cdot \Delta T]}. \quad (10)$$

The opposite prediction «hazardous rock state» according to the developed model (9) looks like:

$$\left[(K_B > K_B^*) \cdot (K_S > K_S^*) \right]_{t \in [t_0, t_0 + \Delta T]} + (K_B > K_B^*)_{t \in [t_1, t_1 + 2 \cdot \Delta T]}. \quad (11)$$

The numerical estimation of the type I errors probabilities has been made involving statistical data accumulated at different regions of coal mining [5]. The type I errors probabilities decreased up to 1,5—2,1 time approximately on making decision «not hazardous rock state» (10). Let us prove it.

The type I error probability while using only the criterion (1) is 0,05—0,47 for various coal mines according to experimental data, thus, $\alpha_1 \in [0,05; 0,47]$. Then the type I error probability in the criterion (2) can be as follows: 1) $\alpha_2 \leq 0,47$, 2) $\alpha_2 > 0,47$.

The variant «not hazardous rock state» according to the model (6) provides the type I error probability decreasing in $\frac{1}{\alpha_{2(1)}}$ time according to expression (7), where $\alpha_{2(1)}$ is the type I error probability in the criterion (2) respectively under the condition that the type I error also has occurred according to the criterion (1).

If $\alpha_2 \leq 0,47$ then the “conditional” probability of the type I error probability $\alpha_{2(1)}$ can also take values that are less, equal or greater than 0,47. Let us discuss cases $\alpha_{2(1)} \leq 0,47$ and $\alpha_{2(1)} > 0,47$. The probability of decreasing the type I error according to the scenario (6) is estimated

by the following inequalities: $\frac{1}{\alpha_{2(1)}} \geq 2,13$ and $1 < \frac{1}{\alpha_{2(1)}} < 2,13$ respectively.

Let us discuss another case, when the type I error probability in the criterion (2) is $\alpha_2 > 0,47$.

Making similar reasoning, we get the same inequalities $\frac{1}{\alpha_{2(1)}} \geq 2,13$ and $1 < \frac{1}{\alpha_{2(1)}} < 2,13$.

Hence, without loss of generality, we consider that type I error probability while decision-making according to the model (6) decreases up to 1,5—2,1 time.

Conclusions and Path Forward

New two-criteria technics has been developed to forecast the gas-dynamic phenomena based on seismic-acoustic signals in rock mass. The probability of the forecast error has been estimated based on simulating different probability scenario. Due to probability estimation the best combination of criteria has been chosen. We proved that the prediction «not hazardous rock state» according to the developed criterion (10) has the probability of a type I error less than prediction according to the criterion (1).

The proposed two-criteria prediction technics with identifying situations «not hazardous rock state» according to (10) and «hazardous rock state» according to (11) has been incorporated in the hardware and software of seismic-acoustic complex at coal mines “Toretska”, “Tsentralna” (Ukraine, Donetsk region, Toretsk).

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ЙМОВІРНІСНА МОДЕЛЬ ОЦІНКИ ПОМИЛОК СЕЙСМОАКУСТИЧНОГО ПРОГНОЗУ ПРИ ВИДОБУТКУ ВУГІЛЛЯ

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Реферат

На даний час для прогнозування вибухів гірських порід у вугільних шахтах широко застосовується сейсмоакустичний метод. Тим не менше, середній рівень надійності цього методу становить близько 60—70 %. Імовірність помилок II роду («помилково негативні») при прогнозуванні становить близько 3 %. Але наявність помилок I роду («помилково позитивні») може бути значним. Ймовірність виникнення таких помилок слід зменшити, але в той же час збільшуються помилки II роду («помилково негативні»), що слід виключити.

Для вдосконалення техніки прогнозу була розроблена прогностична модель, що включає два показники: показник

$$K_{\text{в}} = \frac{A_{\text{в}}}{A_{\text{н}}},$$

де $A_{\text{в}}$ — високочастотна амплітуда в спектрі акустичного сигналу, $A_{\text{н}}$ — низькочастотна амплітуда в спектрі акустичного сигналу, та показник

$$K_S = \frac{S_{\text{в}}}{S},$$

де $S_{\text{в}}$ є площею спектра, що відповідає високочастотній компоненті спектру акустичного сигналу, S є загальна площа амплітудно-частотного спектра сигналу. Відповідно, слід визначити два критерії для виявлення небезпечної ситуації: $K_{\text{в}} = \frac{A_{\text{в}}}{A_{\text{н}}} \geq K_{\text{в}}^*$ у проміжок часу Δt і більше,

та $K_S = \frac{S_{\text{в}}}{S} \geq K_S^*$, де $K_{\text{в}}^*$ — критичне значення прогностичного показника $K_{\text{в}}$, K_S^* є критичним значенням прогностичного показника K_S .

Відається перевага моделі з двома критеріями, що забезпечує зменшення ймовірності помилок першого роду («помилково позитивні»).

Запропоновані критерії (моделі прийняття рішень) застосовані при розробці шахтного сейсмоакустичного апаратно-програмного комплексу.

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