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The case of occurrence of hydraulic impact in a pipe is considered at influence of the allocated non-stationary loading as a variable field of mass forces of the any form. For the description of process the non-stationary allocated one-dimensional model is used. As the initial data the cable equations are accepted. Any change of an overload is approximated with the help of step function. The analytical decision is received with the help of Laplace transformation.

Key words: hydraulic impact, a negative overload, the cable equations, the non-stationary influence, the distributed(allocated) model.

« (1899 .)» [1], [2-4].

$$1 / 2, 2 / 2 \quad 4 / 2 \quad 7, 8 \quad 9 \quad [5].$$

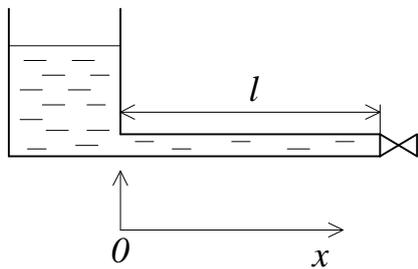
$$[2]. \quad \begin{cases} -\frac{\partial \bar{p}}{\partial x} = \dots \frac{\partial w}{\partial t} + \dots \cdot j(t) \\ -\frac{\partial \bar{p}}{\partial t} = \dots \cdot c^2 \cdot \frac{\partial w}{\partial x} \end{cases} \quad (1)$$

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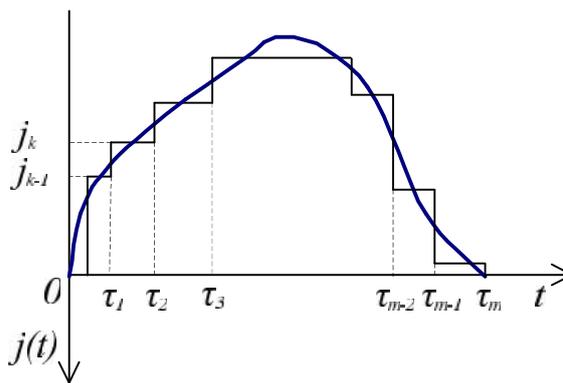
$$t=0 \quad \begin{matrix} \bar{p}=0 \\ w=0 \end{matrix} \quad ; \quad \begin{matrix} x=0 \quad \bar{p}=0 \\ x=l \quad w=0 \end{matrix}$$

$$c - \quad ;$$

$$\bar{p} - \quad ; \\ w -$$



. 1.



. 2.

$j(t)$

$j(t)$

(. 2).
[6]

$$j(t) \overset{\Delta}{=} j(s) = \sum_{k=1}^{m+1} \frac{k}{s} e^{-k s}, \tag{2}$$

$$\begin{aligned}
 & k - , \\
 & k - (\quad), \\
 & k = j_k - j_{k-1}, \\
 & j_0 = 0, \\
 & j_{m+1} = 0, \\
 & m + 1 - , \\
 & m - , \\
 & : \\
 & 1 = j_1 \\
 & m + 1 = -j_m \\
 & : \\
 & (1)
 \end{aligned}$$

$$\begin{cases}
 -\frac{dp(s)}{d(x)} = \dots s \cdot w(s) + \dots \sum \frac{u_k}{s} e^{-k s} \\
 -s \cdot p(s) = \dots c^2 \frac{dw(s)}{d(x)},
 \end{cases} \tag{3}$$

$$\begin{cases} p(s) = -\frac{A \dots}{\xi} \cdot \frac{sh(\xi x)}{ch(\xi l)} \\ w(s) = \frac{A}{s} \cdot \frac{ch(\xi x)}{ch(\xi l)} - \frac{A}{s}, \end{cases} \quad (4)$$

$$\omega^2 = \frac{s^2}{c^2},$$

$$= \sum \frac{k}{s} e^{-ks},$$

$$\begin{cases} p(s) = -\dots c \sum u_k \cdot \frac{sh\left(\frac{s}{c}x\right)}{s^2 \cdot ch\left(\frac{s}{c}l\right)} \cdot e^{-ks} \\ w(s) = \sum u_k \cdot \frac{ch\left(\frac{s}{c}x\right) - ch\left(\frac{s}{c}l\right)}{s^2 \cdot ch\left(\frac{s}{c}l\right)} \cdot e^{-ks}, \end{cases} \quad (5)$$

(5)

$$\Sigma e^{-ks}.$$

(1)

$$\begin{aligned} p(t, x) = & -x \cdot \sum_{k=1}^{m+1} k [u(t-k)] + l \cdot \frac{8}{2} \cdot \sum_{k=1}^{m+1} k [u(t-k)] \cdot \sum_{n=1}^{\infty} \frac{1}{(2n-1)^2} (-1)^{n+1} \times \\ & \times \sin\left[\frac{x}{l}(2n-1)\frac{1}{2}\right] \cdot \cos\left[\frac{c}{l}(2n-1)\frac{1}{2}(t-k)\right] \end{aligned} \quad (6)$$

$$\begin{aligned} w(t, x) = & (-1) \cdot \frac{l}{c} \cdot \frac{8}{2} \cdot \sum_{k=1}^{m+1} k [u(t-k)] \times \\ & \times \sum_{n=1}^{\infty} \frac{1}{(2n-1)^2} \cdot (-1)^{n+1} \cdot \cos\left[\frac{x}{l}(2n-1)\frac{1}{2}\right] \cdot \cos\left[\frac{c}{l}(2n-1)\frac{1}{2}(t-k)\right] \end{aligned} \quad (7)$$

$$x = l \begin{pmatrix} x = l - & ; \\ x = 0 - & \end{pmatrix}$$

$$\left. \begin{aligned} w(t, l) &= 0 \\ p(t, 0) &= 0 \end{aligned} \right\}$$

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$$p(t, l) = -l \sum_{k=1}^{m+1} k [u(t - k)] + l \frac{8}{2} \sum_{k=1}^{m+1} k [u(t - k)] \sum_{n=1}^{\infty} \frac{1}{(2n-1)^2} \cos \left[\frac{c}{l} (2n-1) \frac{(t - k)}{2} \right]$$

$$\dots (-1)^{k+1} \sin \left[\frac{c}{l} (2n-1) \frac{(t - k)}{2} \right] = 1,$$

$$p(t, l) = l \sum_{k=1}^{m+1} k [u(t - k)] \left(-1 + \frac{8}{2} \sum_{n=1}^{\infty} \frac{1}{(2n-1)^2} \cos \left[\frac{c}{l} (2n-1) \frac{(t - k)}{2} \right] \right). \quad (8)$$

$$= \frac{c}{l} \cdot \frac{1}{2}$$

$$p(t, l) = l \sum_{k=1}^{m+1} k [u(t - k)] \left(-1 + \frac{8}{2} \sum_{n=1}^{\infty} \frac{1}{(2n-1)^2} \cos \left[(2n-1) \cdot \cdot (t - k) \right] \right). \quad (9)$$

:

$$l \sum_{k=1}^{m+1} k [u(t - k)]$$

(

);

(-1)

;

$$\frac{8}{2} \sum_{n=1}^{\infty} \frac{1}{(2n-1)^2} \cos \left[(2n-1) \cdot \cdot (t - k) \right]$$

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$$= \frac{c}{2} = \frac{c}{4l}$$

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[5],

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