

Warped product semi-slant submanifolds in locally conformal Kaehler manifolds II

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Abstract. In 1994 N. Papaghiuc introduced the notion of semi-slant submanifold in a Hermitian manifold which is a generalization of CR - and slant-submanifolds, [4], [10]. In particular, he considered this submanifold in Kaehlerian manifolds, [13]. Then, in 2007, V. A. Khan and M. A. Khan considered this submanifold in a nearly Kaehler manifold and obtained interesting results, [9].

Recently, we considered semi-slant submanifolds in a locally conformal Kaehler manifold and we gave a necessary and sufficient conditions of the two distributions (holomorphic and slant) be integrable. Moreover, we considered these submanifolds in a locally conformal Kaehler space form.

In the last paper, we defined 2-kind warped product semi-slant submanifolds in almost hermitian manifolds and studied the first kind submanifold in a locally conformal Kaehler manifold. Using Gauss equation, we derived some properties of this submanifold in an locally conformal Kaehler space form, [3], [11].

In this paper, we consider same submanifold with the parallel second fundamental form in a locally conformal Kaehler space form. Using Codazzi equation, we partially determine the tensor field P which defined in (1.2), see Theorem 4.1. Finally, we show that, in the first type warped product semi-slant submanifold in a locally conformal space form, if it is normally flat, then the shape operators A satisfy some special equations, see Theorem 5.2.

Анотація. В 1994 році Н Папагіук ввів поняття напівпохилого (semi-slant) підмноговиду що є зануреним у ермітовий многовид. Такі підмноговиди є узагальненням CR -підмноговидів та похилих (slant) підмноговидів. На цих многовидах дотичне розшарування є прямою сумою голоморфного та похилого розподілів, [4], [10]. Зокрема, він розглядав таку структуру як підмноговид келерового многовиду, [13]. Згодом, у 2007 році В. А. Хан, та М. А. Хан досліджували такий підмноговид, занурений у наближено келеровий многовид, та отримали цікаві результати, [9].

Нещодавно, автором було досліджено напівпохилі підмноговиди занурені у локально конформно-келерові многовиди і отримано необхідні та

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достатні умови інтегровності обох розподілів (голоморфного та похилого). Крім того, вивчались напівпохилі підмноговиди локально конформно-келерової просторової форми.

В останній статті автором введено два типи напівпохилих підмноговидів, що є викривленими добутками, занурених у майже ермітові многовиди та досліджено підмноговиди першого типу в локально конформно-келерових многовидах. Використовуючи рівняння Гауса, ми отримали деякі властивості такого підмноговиду локально конформно-келерової просторової форми, [3], [11].

В представлені роботі розглядаються напівпохилі підмноговиди локально конформно-келерових просторових форм, які мають паралельну другу фундаментальну форму. За допомогою рівняння Кодацці знайдено вигляд тензору P , що визначений у (1.2) (див. Теорему 4.1). Отримано умови на оператор Вейнгартена A за яких напівпохилий підмноговид локально конформно-келерової просторової форми є викривленим добутком з плоскою нормальною зв'язністю, (див. Теорему 5.2).

1. INTRODUCTION

A Hermitian manifold \tilde{M} with structure (J, \tilde{g}) is called a *locally conformal Kaehler* (an l.c.K. manifold) if each point $x \in \tilde{M}$ has an open neighborhood U with a differentiable function $\rho : U \rightarrow \mathbb{R}$ such that $\tilde{g}^* = e^{-2\rho}\tilde{g}|_U$ is a Kaehlerian metric on U , that is, $\nabla^* J = 0$, where J is an almost complex structure, \tilde{g} is a Hermitian metric, ∇^* is the covariant differentiation with respect to \tilde{g}^* , and \mathbb{R} is a real number space, [14], [10].

Proposition 1.1. *A Hermitian manifold \tilde{M} with structure (J, \tilde{g}) is an l.c.K.-manifold if and only if there exists a global closed 1-form α , called **Lee form**, satisfying*

$$(\tilde{\nabla}_V J)U = -\tilde{g}(\alpha^\sharp, U)JV + \tilde{g}(V, U)\beta^\sharp + \tilde{g}(JV, U)\alpha^\sharp - \tilde{g}(\beta^\sharp, U)V$$

for any $V, U \in T\tilde{M}$, where $\tilde{\nabla}$ denotes the covariant differentiation with respect to \tilde{g} , α^\sharp is the dual vector field of α , the 1-form β is defined by $\beta(X) = -\alpha(JX)$, β^\sharp is the dual vector field of β , and $T\tilde{M}$ is the tangent bundle of \tilde{M} .

An l.c.K.-manifold $\tilde{M}(J, \tilde{g}, \alpha)$ is called an *l.c.K.-space form* if it has a constant holomorphic sectional curvature. Then, [9], the Riemannian curvature tensor \tilde{R} with respect to \tilde{g} of an l.c.K.-space form with the constant holomorphic sectional curvature c is given by the following formula:

$$\begin{aligned} 4\tilde{R}(X, Y, Z, W) = & c\{\tilde{g}(X, W)\tilde{g}(Y, Z) - \tilde{g}(X, Z)\tilde{g}(Y, W) + \\ & + \tilde{g}(JX, W)\tilde{g}(JY, Z) - \tilde{g}(JX, Z)\tilde{g}(JY, W) - \\ & - 2\tilde{g}(JX, Y)\tilde{g}(JZ, W)\} + \end{aligned}$$

$$\begin{aligned}
& + 3\{P(X, W)\tilde{g}(Y, Z) - P(X, Z)\tilde{g}(Y, W) + \\
& \quad + \tilde{g}(X, W)P(Y, Z) - \tilde{g}(X, Z)P(Y, W)\} + \quad (1.1) \\
& - P(JX, W)\tilde{g}(JY, Z) + P(JX, Z)\tilde{g}(JY, W) + \\
& - \tilde{g}(JX, W)P(JY, Z) + \tilde{g}(JX, Z)P(JY, W) + \\
& + 2\{P(JX, Y)\tilde{g}(JZ, W) + \tilde{g}(JX, Y)P(JZ, W)\}
\end{aligned}$$

for any $X, Y, Z, W \in T\tilde{M}$, where P is defined by

$$P(X, Y) = -(\tilde{\nabla}_X \alpha)Y - \alpha(X)\alpha(Y) + \frac{1}{2}\|\alpha\|^2\tilde{g}(X, Y), \quad (1.2)$$

for any $X, Y \in T\tilde{M}$, where $\|\alpha\|$ is the length of the Lee form α with respect to g .

Let $(M, g) = M_1 \otimes_f M_2$ be a warped product Riemannian manifold of (M_1, g_1) and (M_2, g_2) with a warping function f , [12]. Then g is given by

$$g(U, V) = e^{f^2}g_1(\pi_{1*}U, \pi_{1*}V) + g_2(\pi_{2*}U, \pi_{2*}V) \quad (1.3)$$

for any $U, V \in TM$, where π_1 (resp. π_2) denotes the projection operator of M to M_1 (resp. M_2) and π_{1*} (resp. π_{2*}) is the differential of π_1 (resp. π_2).

Let ∇ , ∇_1 and ∇_2 be the covariant differentiation with respect to g , g_1 and g_2 , respectively. Then we have from (1.3)

$$\begin{aligned}
\nabla_X Y &= \nabla_1 X Y - f^2 e^{f^2} g_1(X, Y)(\Delta_2 \log f), \\
\nabla_X Z &= \nabla_Z X = f^2 (Z \log f) X, \\
\nabla_Z W &= \nabla_2 Z W
\end{aligned} \quad (1.4)$$

for any $X, Y \in TM_1$ and $Z, W \in TM_2$, where we put

$$(\Delta_2 \log f)(Z) = (d_2 \log f)(Z).$$

By virtue of (1.3) and (1.4), the curvature tensor form $R(X, Y, Z, W)$ is given by

$$\begin{aligned}
R(X_1, X_2, X_3, X_4) &= e^{f^2} \left[R_1(X_1, X_2, X_3, X_4) - \right. \\
& \quad \left. - f^4 e^{f^2} \|\nabla_2 \log f\|^2 \{g_1(X_1, X_4)g_1(X_2, X_3) - \right. \\
& \quad \left. - g_1(X_1, X_3)g_1(X_2, X_4)\} \right], \\
R(X_1, Z_1, Z_2, X_2) &= -f^2 e^{f^2} \{(2 + f^2)(Z_2 \log f)(Z_1 \log f) + \\
& \quad + \nabla_2 Z_1 \nabla_2 Z_2 \log f\} g_1(X_1, X_2), \\
R(Z_1, Z_2, Z_3, Z_4) &= R_2(Z_1, Z_2, Z_3, Z_4), \\
Other &= 0,
\end{aligned} \quad (1.5)$$

for any $X_1, X_2, X_3, X_4 \in TM_1$ and $Z_1, Z_2, Z_3, Z_4 \in TM_2$, where R_1 and R_2 be the Riemannian curvature forms with respect to g_1 and g_2 , respectively. Next, using (1.5), the Ricci tensor $\rho(U, V)$ is separated as

$$\rho(X_1, X_2) = \rho_1(X_1, X_2) - f^2 e^{f^2} \{ (2 + n_1 f^2) \|\nabla_2 \log f\|^2 + \delta_2 d_2 \log f \} g_1(X_1, X_2),$$

$$\rho(X_1, Z_1) = 0,$$

$$\rho(Z_1, Z_2) = \rho_2(Z_1, Z_2) - n_1 f^2 \{ (2 + f^2) (\nabla_{2Z_1} \log f) (\nabla_{2Z_2} \log f) + \nabla_{2Z_1} \nabla_{2Z_2} \log f \},$$

where ρ_1 (resp. ρ_2) denotes the Ricci tensor with respect to g_1 (resp. g_2). Finally, if we respectively put τ, τ_1 and τ_3 the scalar curvature with respect to g, g_1 and g_2 . It easily follows that

$$\tau = e^{f^2} \tau_1 + \tau_2 - (n_1 - 1) n_1 f^4 \|\nabla_2 \log f\|^2.$$

2. SEMI-SLANT-SUBMANIFOLDS IN AN ALMOST HERMITIAN MANIFOLD.

In general, for a Riemannian manifold (\tilde{M}, \tilde{g}) and its Riemannian submanifold (M, g) we know the Gauss and Weingarten formulas

$$\tilde{\nabla}_X Y = \nabla_X Y + \sigma(X, Y), \quad \tilde{\nabla}_X N = -A_N X + \nabla^\perp_X N$$

for all $X, Y \in TM$ and $N \in T^\perp M$, where ∇ is the covariant differentiation with respect to g , σ is the second fundamental form, and A_N is the shape operator or the fundamental tensor of Weingarten with respect to N and ∇^\perp is normal connection, [5], [6]. Also the following identity holds true:

$$\tilde{g}(A_N Y, X) = \tilde{g}(\sigma(Y, X), N).$$

The Codazzi equation and the Ricci equation are respectively given by

$$\tilde{R}(U, V, W, N_1) = \tilde{g}((\bar{\nabla}_U \sigma)(V, W) - (\bar{\nabla}_V \sigma)(U, W), Z), \quad (2.1)$$

$$\tilde{R}(U, V, N_1, N_2) = R^\perp(U, V, N_1, N_2) - \tilde{g}([A_{N_1}, A_{N_2}]U, V) \quad (2.2)$$

for all $U, V, W, Z \in TM$ and $N_1, N_2 \in T^\perp M$, where R^\perp is the normal curvature tensor, and

$$(\bar{\nabla}_U \sigma)(V, W) = \nabla^\perp_{UV} \sigma(V, W) - \sigma(\nabla_U V, W) - \sigma(V, \nabla_U W).$$

The second fundamental form σ is called *parallel* if it satisfies $\bar{\nabla} \sigma = 0$ identically. Also a submanifold M is said to be totally geodesic whenever $\sigma = 0$ on M .

Let $(M, g) = (M_1, g_1) \otimes_f (M_2, g_2)$ be a warped product submanifold of (\tilde{M}, \tilde{g}) . Then the induced metric tensor g of \tilde{g} is given by

$$g(U, V) = e^{f^2} g_1(\pi_{1*}U, \pi_{1*}V) + g_2(\pi_{2*}U, \pi_{2*}V)$$

for any $U, V \in TM$. A warped product submanifold M is called M_1 (resp. M_2) *geodesic* if the second fundamental form satisfies $\sigma(X, Y) = 0$ (resp. $\sigma(Z, W) = 0$) for all $X, Y \in TM_1$ and $Z, W \in TM_2$. Moreover M is said to be *mixed totally geodesic* if the second fundamental form σ satisfies $\sigma(X, Z) = 0$ for all $X \in TM_1$ and $Z \in TM_2$.

By virtue of (1.5) and the Gauss equation, we have

$$\begin{aligned} \tilde{R}(X_1, X_2, X_3, X_4) &= e^{f^2} \{ R_1(X_1, X_2, X_3, X_4) - \\ &\quad - f^4 e^{f^2} \|\log f\|^2 (g_1(X_1, X_4)g_1(X_2, X_3) - g_1(X_1, X_3)g_1(X_2, X_4)) \} + \\ &\quad + \tilde{g}(\sigma(X_1, X_4), \sigma(X_2, X_3)) - \tilde{g}(\sigma(X_1, X_3), \sigma(X_2, X_4)), \\ \tilde{R}(X_1, X_2, X_3, Z_1) &= \tilde{g}(\sigma(X_1, Z_1), \sigma(X_2, X_3)) - \tilde{g}(\sigma(X_1, X_3), \sigma(X_2, Z_1)), \\ \tilde{R}(X_1, X_2, Z_1, Z_2) &= \tilde{g}(\sigma(X_1, Z_2), \sigma(X_2, Z_1)) - \tilde{g}(\sigma(X_1, Z_1), \sigma(X_2, Z_2)), \\ \tilde{R}(X_1, Z_1, Z_2, X_2) &= -f^2 e^{f^2} \{ (2 + f^2)(Z_1 \log f)(Z_2 \log f) + \\ &\quad + \nabla_{2Z_2} \nabla_{2Z_1} \log f \} g_1(X_1, X_2) + \tilde{g}(\sigma(X_1, X_2), \sigma(Z_1, Z_2)) - \\ &\quad - \tilde{g}(\sigma(X_1, Z_2), \sigma(Z_1, X_2)), \\ \tilde{R}(X_1, Z_1, Z_2, Z_3) &= \tilde{g}(\sigma(X_1, Z_3), \sigma(Z_1, Z_2)) - \tilde{g}(\sigma(X_1, Z_2), \sigma(Z_1, Z_3)), \\ \tilde{R}(Z_1, Z_2, Z_3, Z_4) &= R_2(Z_1, Z_2, Z_3, Z_4) + \tilde{g}(\sigma(Z_1, Z_4), \sigma(Z_2, Z_3)) - \\ &\quad - \tilde{g}(\sigma(Z_1, Z_3), \sigma(Z_2, Z_4)), \end{aligned}$$

for all $X_1, X_2, X_3, X_4 \in TM_1$ and $Z_1, Z_2, Z_3, Z_4 \in TM_2$.

For a vector field $U \in TM$, the angle between JU and TM is called the *Wirtinger angle* of U .

A differentiable distribution $\mathcal{D}^\theta : x \rightarrow \mathcal{D}^\theta_x$ on M is said to be a *slant* one if for each $U_x \in \mathcal{D}^\theta_x$, the Wirtinger angle of U_x is constant ($= \theta$) for any $x \in M$. In this case, the Wirtinger angle is said to be the *slant angle*. In particular, if TM is slant, then the submanifold is called *slant* as well. A slant submanifold is holomorphic (resp. totally real) if its slant angle $\theta = 0$ (resp. $\theta = \frac{\pi}{2}$). A slant submanifold is said to be *proper* if it is not holomorphic nor totally real.

A submanifold M in \tilde{M} is called *semi-slant* if there exists a differentiable distribution $\mathcal{D} : x \rightarrow \mathcal{D}_x \subset T_x M$ on M satisfying the following conditions

- (i) \mathcal{D} is holomorphic, i.e., $J\mathcal{D}_x = \mathcal{D}_x$ for each $x \in M$ and
- (ii) the complementary orthogonal distribution $\mathcal{D}^\theta : x \rightarrow \mathcal{D}^\theta_x \subset T_xM$ is slant with slant angle θ , where T_xM means the tangent vector space of M at x , [7].

Remark 2.1. A semi-slant submanifold is a CR -submanifold if the slant angle is equal to $\frac{\pi}{2}$, e.g. [1], [2], [8].

In a submanifold M of an almost Hermitian manifold $\tilde{M}(J, \tilde{g})$, for all $U \in TM$ and $\xi \in T^\perp M$, we write

$$JU = TU + FU, \quad J\xi = t\xi + f\xi,$$

where TU (resp. FU) is the tangential (resp. normal) component of JU and $t\xi$ (resp. $f\xi$) is the tangential (resp. normal) component of $J\xi$.

Then one can easily check the following relations:

$$\begin{aligned} T^2 + tF &= -I, & f^2 + Ft &= -I \\ FT + fF &= 0, & tF + Tt &= 0. \end{aligned} \quad (2.3)$$

For a semi-slant submanifold M of an almost Hermitian manifold \tilde{M} the tangent bundle TM and the normal bundle $T^\perp M$ of M are decomposed as

$$TM = \mathcal{D} \oplus \mathcal{D}^\theta, \quad T^\perp M = F\mathcal{D}^\theta \oplus \nu,$$

where ν denotes the orthogonal complementary distribution of $F\mathcal{D}^\theta$ in $T^\perp M$.

Next, for an element $U \in TM$ in a semi-slant submanifold M , we write

$$U = T_1U + T_2U, \quad (2.4)$$

where T_1U (resp. T_2U) denotes the \mathcal{D} (resp. \mathcal{D}^θ) component of U .

It follows from (2.3) and (2.4) that

$$JU = JT_1U + TT_2U + FT_2U, \quad (2.5)$$

where $JT_1U \in \mathcal{D}$, $TT_2U \in \mathcal{D}^\theta$ and $FT_2U \in F\mathcal{D}^\theta \subset T^\perp M$. Thus if we put

$$PU = JT_1U + TT_2U \quad (2.6)$$

for any $U \in TM$, then

$$P^2U = -T_1U - T_2U - tFT_2U \quad (2.7)$$

for any $U \in TM$.

Now we easily get from (2.7) the following statement:

Proposition 2.2. *In a semi-slant submanifold of an almost Hermitian manifold \tilde{M} , the operator P defined by (2.6) is an almost complex structure in the holomorphic distribution \mathcal{D} .*

The covariant differentiation $\bar{\nabla}$ of T_1 , T_2 , T , F , t and f are defined as follows:

$$\begin{aligned}(\bar{\nabla}_U T_1)V &= \nabla_U(T_1V) - T_1\nabla_U V, & (\bar{\nabla}_U T_2)V &= \nabla_U(T_2V) - T_2\nabla_U V, \\(\bar{\nabla}_U T)V &= \nabla_U(TV) - T\nabla_U V, & (\bar{\nabla}_U F)V &= \nabla_U^\perp(FV) - F\nabla_U V, \\(\bar{\nabla}_U t)\xi &= \nabla_U(t\xi) - t\nabla_U^\perp\xi, & (\bar{\nabla}_U f)\xi &= \nabla_U^\perp(f\xi) - f\nabla_U^\perp\xi\end{aligned}$$

where $U, V \in TM$ and $\xi \in T^\perp M$.

Moreover, if we define the covariant differentiation $\bar{\nabla}$ of P by

$$(\bar{\nabla}_U P)V = \nabla_U(PV) - P\nabla_U V$$

then

$$\begin{aligned}(\bar{\nabla}_U P)V &= (\tilde{\nabla}_U J)T_1V + J(\bar{\nabla}_U T_1)V + (\bar{\nabla}_U T)(T_2V) + \\ &+ T(\bar{\nabla}_U T_2)V + J\sigma(U, T_1V) - \sigma(U, JT_1V).\end{aligned}$$

Write

$$(\tilde{\nabla}_U J)V = \mathcal{P}_U V + \mathcal{Q}_U V,$$

where $\mathcal{P}_U V$ (resp. $\mathcal{Q}_U V$) denotes the tangential (resp. normal) part of $(\tilde{\nabla}_U J)V$.

V. A. Khan and M. A. Khan proved the following statement:

Proposition 2.3. [9]. *The holomorphic distribution \mathcal{D} on a semi-slant submanifold of an almost Hermitian manifold is integrable if and only if*

$$\mathcal{Q}_X Y - \mathcal{Q}_Y X = \sigma(X, TY) - \sigma(Y, TX)$$

for any $X, Y \in \mathcal{D}$. The slant distribution \mathcal{D}^θ on a semi-slant submanifold of an almost Hermitian manifold is integrable if and only if

$$T_1(\nabla_Z TW - \nabla_W TZ + A_{FZ}W - A_{FW}Z + \mathcal{P}_W Z - \mathcal{P}_Z W) = 0$$

for any $Z, W \in \mathcal{D}^\theta$.

Using these proposition, we proved the following result:

Theorem 2.4. [11]. (I) *The holomorphic distribution \mathcal{D} of a semi-slant submanifold M in an l.c.K.-manifold $\tilde{M}(J, \tilde{g}, \alpha)$ is integrable if and only if*

$$\sigma(X, TY) - \sigma(Y, TX) = 2\tilde{g}(TX, Y)\alpha_2^\sharp$$

(II) *The slant distribution \mathcal{D}^θ of a semi-slant submanifold M in an l,c,K.-manifold $\tilde{M}(J, \tilde{g}, \alpha)$ is integrable if and only if*

$$\begin{aligned}T_1(\nabla_Z TW - \nabla_W TZ + A_{FZ}W - A_{FW}Z + \\ + \tilde{g}(\alpha_1^\sharp, W)TZ - \tilde{g}(\alpha_1^\sharp, Z)TW + 2\tilde{g}(TW, Z)\alpha_1^\sharp) = 0\end{aligned}$$

or equivalently

$$T_1\{(\bar{\nabla}_Z T)W - (\bar{\nabla}_W T)Z + T[Z, W] + A_{FZ}W - A_{FW}Z + \\ + \tilde{g}(\alpha_1^\sharp, W)TZ - \tilde{g}(\alpha_1^\sharp, Z)TW + 2\tilde{g}(TW, Z)\alpha_1^\sharp\} = 0,$$

where $Z, W \in \mathcal{D}^\theta$, and $[Z, W]$ is the Lie bracket of Z and W .

3. WARPED PRODUCT SEMI-SLANT SUBMANIFOLDS IN AN L.C.K.-MANIFOLD

Let M be a semi-slant submanifold of an almost Hermitian manifold $\tilde{M}(J, \tilde{g})$. Suppose that the distributions \mathcal{D} and \mathcal{D}^θ are integrable, and let $M_{\mathcal{D}}$ (resp. $M_{\mathcal{D}^\theta}$) be the maximal integral submanifold of \mathcal{D} (resp. \mathcal{D}^θ). Then M is a product manifold of $M_{\mathcal{D}}$ and $M_{\mathcal{D}^\theta}$, that is,

$$M = M_{\mathcal{D}} \otimes M_{\mathcal{D}^\theta}. \quad (3.1)$$

Therefore we can write

$$T\tilde{M} = TM_{\mathcal{D}} \oplus TM_{\mathcal{D}^\theta} \oplus FTM_{\mathcal{D}^\theta} \oplus \nu, \quad (3.2)$$

where ν is the complementary orthogonal subbundle of $FTM_{\mathcal{D}^\theta} = F\mathcal{D}^\theta$ in $T^\perp M$. We will call the submanifold $M_{\mathcal{D}}$ (resp. $M_{\mathcal{D}^\theta}$) the *holomorphic* (resp. *slant*) *component* of M .

Given a differentiable function f_1 (resp. f_2) on $M_{\mathcal{D}^\theta}$ (resp. $M_{\mathcal{D}}$), define the following warped product submanifolds

$$M_1 = M_{\mathcal{D}} \otimes_{f_1} M_{\mathcal{D}^\theta}, \quad M_2 = M_{\mathcal{D}^\theta} \otimes_{f_2} M_{\mathcal{D}}. \quad (3.3)$$

We say that M_1 (resp. M_2) is the *first* (resp. *second*) *type warped product semi-slant submanifold* of an almost Hermitian manifold.

In this paper, we mainly consider the first type warped product semi-slant submanifold in an l.c.K.-manifold.

Let M be the first type warped product semi-slant submanifold in an l.c.K.-manifold \tilde{M} . Then the induced metric tensor g in M of \tilde{M} is given by

$$g(U, V) = e^{f^2} g_{\mathcal{D}}(\pi_{\mathcal{D}} * U, \pi_{\mathcal{D}} * V) + g_{\mathcal{D}^\theta}(\pi_{\mathcal{D}^\theta} * U, \pi_{\mathcal{D}^\theta} * V) \quad (3.4)$$

for any $U, V \in TM$, where $g_{\mathcal{D}}$ (resp. $g_{\mathcal{D}^\theta}$) denotes the Riemannian metric on $M_{\mathcal{D}}$ (resp. $M_{\mathcal{D}^\theta}$), $\pi_{\mathcal{D}}$ (resp. $\pi_{\mathcal{D}^\theta}$) is the projection operator of M to $M_{\mathcal{D}}$ (resp. $M_{\mathcal{D}^\theta}$) and f is a certain positive differentiable function on $M_{\mathcal{D}^\theta}$.

Now, let $\tilde{\nabla}$, ∇ , $\nabla^{\mathcal{D}}$ and $\nabla^{\mathcal{D}^\theta}$ be the covariant differentiations with respect to \tilde{g} , g , $g_{\mathcal{D}}$ and $g_{\mathcal{D}^\theta}$, respectively. Then by (1.4)

$$\begin{aligned}\nabla_X Y &= \nabla^{\mathcal{D}}_X Y - f^2 e^{f^2} (\Delta_1 \log f) g_{\mathcal{D}}(X, Y), \\ \nabla_X Z &= \nabla_Z X = f^2 (Z \log f) X, \\ \nabla_Z W &= \nabla^{\mathcal{D}^\theta}_Z W,\end{aligned}\tag{3.5}$$

for any $X, Y \in \mathcal{D}$ and $Z, W \in \mathcal{D}^\theta$, where we put

$$\Delta_1 \log f = g_{\mathcal{D}^\theta}{}^{ce} (\partial_c \log f) \partial_e.$$

Let M be a semi-slant submanifold with distributions \mathcal{D} , \mathcal{D}^θ be an almost Hermitian manifold \tilde{M} , $\dim \mathcal{D} = 2p$, $\dim \mathcal{D}^\perp = q$, and $\dim \nu = 2s$. Then we take the following generalized adopted frame in \tilde{M} :

- (1) $\{e_1, e_2, \dots, e_p, e_1^*, e_2^*, \dots, e_p^*\}$ is an orthonormal frame of \mathcal{D} , where $e_i^* = J e_i$ for $i \in \{1, 2, \dots, p\}$;
- (2) $\{e_{2p+1}, e_{2p+2}, \dots, e_{2p+q}\}$ is an orthonormal frame of \mathcal{D}^θ such that the vectors $F e_{2p+1}, F e_{2p+2}, \dots, F e_{2p+q}$ are orthogonal in $F \mathcal{D}^\theta$.
- (3) $\{e_{n+q+1}, e_{n+q+2}, \dots, e_{n+q+s}, e_{n+q+1}^*, e_{n+q+2}^*, \dots, e_{n+q+s}^*\}$ is an orthonormal frame of ν , where $e_{n+q+a}^* = J e_{n+q+a}$ for $a \in \{1, 2, \dots, s\}$;
- (4) $e_{2p+a}^* = \frac{F e_{2p+a}}{\|F e_{2p+a}\|}$ for $a \in \{1, 2, \dots, q\}$.

Hereafter, for a tensor field T of $(0, s)$ -type, we write $T_{\mu_1, \mu_2, \dots, \mu_s}$ instead of $T(e_{\mu_1}, e_{\mu_2}, \dots, e_{\mu_s})$ with respect to the generalized adapted frame.

In the last paper ([11]), using the Gauss equation, we proved

Proposition 3.1. *In a first type warped product semi-slant submanifold in an l.c.K.-space form, the mean curvature $\|H\|$ satisfies the inequality*

$$\begin{aligned}4n\|H\|^2 + 8pf^2 \{ (2p-1)f^2 \|\log f\|^2 + 2(2+f^2) \sum_{a=2p+1}^{2p+q} (e_a \log f)^2 \} + \\ + (n^2 + 2n - 3q)c + 3c \sum_{b,a=2p+1}^{2p+q} \{T_{ba}\}^2 - 4(e^{f^2} \tau^{\mathcal{D}} + \tau^{\mathcal{D}^\theta}) + \\ + 16pf^2 \sum_{b,a=2p+1}^{2p+q} \nabla^{\mathcal{D}^\theta} e_a \nabla^{\mathcal{D}^\theta} e_a \log f + 6(n-2) \sum_{\mu=1}^n P_{\mu\mu} + \\ + 6 \sum_{a=2p+1}^{2p+q} P_{aa} - 6 \sum_{b,a=2p+1}^{2p+q} P(Je_b, e_a) T_{ba} \geq 0.\end{aligned}\tag{3.6}$$

In particular, the equality case of (3.6) is that our submanifold is totally geodesic. Then we have the following equation for the warping function f

$$\begin{aligned}
& 8pf^2\{(2p-1)f^2\|\log f\|^2 + 2(2+f^2)\sum_{a=2p+1}^{2p+q}(e_a\log f)^2\} + \\
& + (n^2 + 2n - 3q)c + 3c\sum_{b,a=2p+1}^{2p+q}\{T_{ba}\}^2 - 4(e^{f^2}\tau^{\mathcal{D}} + \tau^{\mathcal{D}^\theta}) + \\
& + 16pf^2\sum_{b,a=2p+1}^{2p+q}\nabla^{\mathcal{D}^\theta}e_a\nabla^{\mathcal{D}^\theta}e_a\log f + 6(n-2)\sum_{\mu=1}^n P_{\mu\mu} + \\
& + 6\sum_{a=2p+1}^{2p+q}P_{aa} - 6\sum_{b,a=2p+1}^{2p+q}P(Je_b, e_a)T_{ba} = 0.
\end{aligned}$$

From which, we obtain

$$\begin{aligned}
& (n^2 + 2n - 3q)c + 3c\sum_{b,a=2p+1}^{2p+q}\{T_{ba}\}^2 - 4(e^{f^2}\tau^{\mathcal{D}} + \tau^{\mathcal{D}^\theta}) + \\
& + 16pf^2\sum_{b,a=2p+1}^{2p+q}\nabla^{\mathcal{D}^\theta}e_a\nabla^{\mathcal{D}^\theta}e_a\log f + 6(n-2)\sum_{\mu=1}^n P_{\mu\mu} + \\
& + 6\sum_{a=2p+1}^{2p+q}P_{aa} - 6\sum_{b,a=2p+1}^{2p+q}P(Je_b, e_a)T_{ba} \leq 0.
\end{aligned}$$

4. SEMI-SLANT SUBMANIFOLDS WITH THE PARALLEL SECOND FUNDAMENTAL FORM

Using (1.1), the curvature tensor \tilde{R} of the first type warped product semi-slant submanifold M in an l.c.K.-space form $\tilde{M}(c)$ is separated, with respect to the generalized adapted frame, as

$$\begin{aligned}
4\tilde{R}_{jaha^*} &= 3(P_{ja^*}\delta_{ih} - P_{ia^*}\delta_{jh}), \\
4\tilde{R}_{jih^*a^*} &= -P_{j^*a^*}\delta_{ih} + P_{i^*a^*}\delta_{jh}, \\
4\tilde{R}_{ji^*ha^*} &= -3P_{i^*a^*}\delta_{jh} + P_{j^*a^*}\delta_{ih} + 2P_{h^*a^*}\delta_{ji}, \\
4\tilde{R}_{ji^*h^*a^*} &= 3P_{ja^*}\delta_{ih} - P_{ia^*}\delta_{jh} - 2P_{ha^*}\delta_{ji}, \\
4\tilde{R}_{j^*i^*h^*a^*} &= 3(P_{j^*a^*}\delta_{ih} - P_{i^*a^*}\delta_{jh}), \\
2\tilde{R}_{jiba^*} &= P_{j^*i}F_{ba},
\end{aligned}$$

$$\begin{aligned}
2\tilde{R}_{ji^*ba^*} &= -c\delta_{ji}F_{ba} + P_{ji}F_{ba} + (T_b^cP_{ca^*} + F_b^cP_{c^*a^*})\delta_{ji}, \\
2\tilde{R}_{j^*i^*ba^*} &= -P_{ji^*}F_{ba}, \\
4\tilde{R}_{jcb a^*} &= 3P_{ja^*}\delta_{cb} - P_{j^*a^*}T_{cb} + P_{j^*b}F_{ca} + 2P_{j^*c}F_{ba}, \\
4\tilde{R}_{j^*c b a^*} &= 3P_{j^*a^*}\delta_{cb} + P_{ja^*}T_{cb} - P_{jb}F_{ca} - 2P_{jc}F_{ba}, \\
4\tilde{R}_{dc b a^*} &= c(F_{da}T_{cb} - T_{db}F_{ca} - 2T_{dc}F_{ba}) + 3(P_{da^*}\delta_{cb} - P_{ca^*}\delta_{db}) - \\
&\quad - (T_d^cP_{ca^*} + F_d^cP_{c^*a^*})T_{cb} + (T_d^eP_{eb} + F_d^eP_{e^*b})F_{ca} - \\
&\quad - (T_c^eP_{eb} + F_c^eP_{e^*b})F_{da} + (T_c^eP_{ea^*} + F_c^eP_{e^*a^*})T_{db} + \\
&\quad + 2\{(T_d^eP_{ec} + F_d^eP_{e^*c})F_{ba} + (T_b^eP_{ea^*} + F_b^eP_{e^*a^*})T_{dc}\}, \\
4\tilde{R}_{jihr} &= 3(P_{jr}\delta_{ih} - P_{ir}\delta_{jh}), \\
4\tilde{R}_{jih^*r} &= -P_{j^*r}\delta_{ih} + P_{i^*r}\delta_{jh}, \\
4\tilde{R}_{ji^*hr} &= -3P_{i^*r}\delta_{jh} + P_{j^*r}\delta_{ih} + 2P_{h^*r}\delta_{ji}, \\
4\tilde{R}_{ji^*h^*r} &= 3P_{jr}\delta_{ih} - P_{ir}\delta_{jh} - 2P_{hr}\delta_{ji}, \\
4\tilde{R}_{j^*i^*hr} &= -P_{jr}\delta_{ih} + P_{ir}\delta_{jh}, \\
4\tilde{R}_{j^*i^*h^*r} &= 3(P_{j^*r}\delta_{ih} - P_{i^*r}\delta_{jh}), \\
\tilde{R}_{jiar} &= 0, \\
2\tilde{R}_{ji^*ar} &= (T_a^eP_{er} + F_a^eP_{e^*r})\delta_{ji}, \\
\tilde{R}_{j^*i^*ar} &= 0, \\
4\tilde{R}_{jbar} &= 3P_{jr}\delta_{ba} - P_{j^*r}T_{ba}, \\
4\tilde{R}_{j^*bar} &= 3P_{j^*r}\delta_{ba} + P_{jr}T_{ba}, \\
4\tilde{R}_{cbar} &= 3(P_{cr}\delta_{ba} - P_{br}\delta_{ca}) - (T_c^eP_{er} + F_c^eP_{e^*r})T_{ba} \\
&\quad + (T_b^eP_{er} + F_b^eP_{e^*r})T_{ca} + 2(T_a^eP_{er} + F_a^eP_{e^*r})T_{cb}
\end{aligned}$$

for any $j, i, h \in \{1, 2, \dots, p\}$, $d, c, b, a \in \{2p+1, 2p+2, \dots, 2p+q\}$ and $r \in \{n+q+1, n+q+2, \dots, m\}$.

Thus, by virtue of previous formulas the Codazzi equation (2.1) is separated as

$$\begin{aligned}
4\{\tilde{g}(\bar{\nabla}_j\sigma_{ih}, e_a^*) - \tilde{g}(\bar{\nabla}_i\sigma_{jh}, e_a^*)\} &= 3(P_{ja^*}\delta_{ih} - P_{ia^*}\delta_{jh}), \\
4\{\tilde{g}(\bar{\nabla}_j\sigma_{ih^*}, e_a^*) - \tilde{g}(\bar{\nabla}_i\sigma_{jh^*}, e_a^*)\} &= -P_{j^*a^*}\delta_{ih} + P_{i^*a^*}\delta_{jh}, \\
4\{\tilde{g}(\bar{\nabla}_j\sigma_{i^*h}, e_a^*) - \tilde{g}(\bar{\nabla}_i\sigma_{jh}, e_a^*)\} &= -3P_{i^*a^*}\delta_{jh} + P_{j^*a^*}\delta_{ih} + 2P_{h^*a^*}\delta_{ji}, \\
4\{\tilde{g}(\bar{\nabla}_j\sigma_{i^*h^*}, e_a^*) - \tilde{g}(\bar{\nabla}_i\sigma_{jh^*}, e_a^*)\} &= 3P_{ja^*}\delta_{ih} - P_{ia^*}\delta_{jh} - 2P_{ha^*}\delta_{ji}, \\
4\{\tilde{g}(\bar{\nabla}_j\sigma_{i^*h^*}, e_a^*) - \tilde{g}(\bar{\nabla}_i\sigma_{j^*h^*}, e_a^*)\} &= 3(P_{j^*a^*}\delta_{ih} - P_{i^*a^*}\delta_{jh}),
\end{aligned}$$

$$\begin{aligned}
2\{\tilde{g}(\bar{\nabla}_j\sigma_{ib}, e_a^*) - \tilde{g}(\bar{\nabla}_i\sigma_{jb}, e_a^*)\} &= P_{j^*i}F_{ba} \\
2\{\tilde{g}(\bar{\nabla}_j\sigma_{i^*b}, e_a^*) - \tilde{g}(\bar{\nabla}_{i^*}\sigma_{jb}, e_a^*)\} &= -c\delta_{ji}F_{ba} + P_{ji}F_{ba} + \\
&\quad + \{T_b^cP_{ca^*} + F_b^cP_{c^*a^*}\}\delta_{ji}, \\
2\{\tilde{g}(\bar{\nabla}_{j^*}\sigma_{i^*b}, e_a^*) - \tilde{g}(\bar{\nabla}_{i^*}\sigma_{j^*b}, e_a^*)\} &= -P_{j^*i}F_{ba}, \\
4\{\tilde{g}(\bar{\nabla}_j\sigma_{cb}, e_a^*) - \tilde{g}(\bar{\nabla}_c\sigma_{jb}, e_a^*)\} &= 3P_{ja^*}\delta_{cb} - P_{j^*a^*}T_{cb} + \\
&\quad + P_{j^*b}F_{ca} + 2P_{j^*c}F_{ba}, \\
4\{\tilde{g}(\bar{\nabla}_{j^*}\sigma_{cb}, e_a^*) - \tilde{g}(\bar{\nabla}_c\sigma_{j^*b}, e_a^*)\} &= 3P_{j^*a^*}\delta_{cb} + P_{ja^*}T_{cb} - \\
&\quad - P_{jb}F_{ca} - 2P_{jc}F_{ba}, \\
4\{\tilde{g}(\bar{\nabla}_d\sigma_{cb}, e_a^*) - \tilde{g}(\bar{\nabla}_c\sigma_{db}, e_a^*)\} &= c(F_{da}T_{cb} - T_{db}F_{ca} - 2T_{dc}F_{ba}) \\
&\quad + 3(P_{da^*}\delta_{cb} - P_{ca^*}\delta_{db}) - (T_d^eP_{ea^*} + F_d^eP_{e^*a^*})T_{cb} \\
&\quad + (T_d^eP_{eb} + F_d^eP_{be^*})F_{ca} - (T_c^eP_{eb} + F_c^eP_{bc^*})F_{da} \\
&\quad + (T_c^eP_{ea^*} + F_c^eP_{e^*a^*})T_{db} + 2\{(T_d^eP_{ec} + F_d^eP_{ce^*})F_{ba} \\
&\quad + (T_b^eP_{ea^*} + F_b^eP_{e^*a^*})T_{dc}\}, \\
4\{\tilde{g}(\bar{\nabla}_j\sigma_{ih}, e_r) - \tilde{g}(\bar{\nabla}_i\sigma_{jh}, e_r)\} &= 3(P_{jr}\delta_{ih} - P_{ir}\delta_{jh}), \\
4\{\tilde{g}(\bar{\nabla}_j\sigma_{ih^*}, e_r) - \tilde{g}(\bar{\nabla}_i\sigma_{jh^*}, e_r)\} &= -P_{j^*r}\delta_{ih} + P_{i^*r}\delta_{jh}, \\
4\{\tilde{g}(\bar{\nabla}_j\sigma_{i^*h}, e_r) - \tilde{g}(\bar{\nabla}_{i^*}\sigma_{jh}, e_r)\} &= -3P_{i^*r}\delta_{jh} + P_{j^*r}\delta_{ih} + 2P_{h^*r}\delta_{ji}, \\
4\{\tilde{g}(\bar{\nabla}_j\sigma_{i^*h^*}, e_r) - \tilde{g}(\bar{\nabla}_{i^*}\sigma_{jh^*}, e_r)\} &= 3P_{jr}\delta_{ih} - P_{ir}\delta_{jh} - 2P_{hr}\delta_{ji}, \\
4\{\tilde{g}(\bar{\nabla}_{j^*}\sigma_{i^*h}, e_r) - \tilde{g}(\bar{\nabla}_{i^*}\sigma_{j^*h}, e_r)\} &= -P_{j^*r}\delta_{ih} + P_{i^*r}\delta_{jh}, \\
4\{\tilde{g}(\bar{\nabla}_{j^*}\sigma_{i^*h^*}, e_r) - \tilde{g}(\bar{\nabla}_{i^*}\sigma_{j^*h^*}, e_r)\} &= 3(P_{j^*r}\delta_{ih} - P_{i^*r}\delta_{jh}), \\
\tilde{g}(\bar{\nabla}_j\sigma_{ia}, e_r) - \tilde{g}(\bar{\nabla}_i\sigma_{ja}, e_r) &= 0, \\
4\{\tilde{g}(\bar{\nabla}_j\sigma_{i^*a}, e_r) - \tilde{g}(\bar{\nabla}_{i^*}\sigma_{ja}, e_r)\} &= (T_a^cP_{cr} + F_a^cP_{c^*r})\delta_{ji}, \\
\tilde{g}(\bar{\nabla}_{j^*}\sigma_{i^*a}, e_r) - \tilde{g}(\bar{\nabla}_{i^*}\sigma_{j^*a}, e_r) &= 0, \\
4\{\tilde{g}(\bar{\nabla}_j\sigma_{ba}, e_r) - \tilde{g}(\bar{\nabla}_b\sigma_{ja}, e_r)\} &= 3P_{jr}\delta_{ba} - P_{j^*r}T_{ba}, \\
4\{\tilde{g}(\bar{\nabla}_{j^*}\sigma_{ba}, e_r) - \tilde{g}(\bar{\nabla}_{b^*}\sigma_{ja}, e_r)\} &= 3P_{j^*r}\delta_{ba} + P_{jr}T_{ba}, \\
4\{\tilde{g}(\bar{\nabla}_c\sigma_{ba}, e_r) - \tilde{g}(\bar{\nabla}_b\sigma_{ca}, e_r)\} &= 3(P_{cr}\delta_{ba} - P_{br}\delta_{ca}) - \\
&\quad - (T_c^eP_{er} + F_c^eP_{e^*r})T_{ba} + (T_b^eP_{er} + F_b^eP_{e^*r})T_{ca} + \\
&\quad + 2(T_a^eP_{er} + F_a^eP_{e^*r})T_{cb},
\end{aligned}$$

for all $j, i, h \in \{1, 2, \dots, p\}$, $d, c, b, a \in \{2p + 1, 2p + 2, \dots, 2p + q\}$ and $r \in \{n + q + 1, n + q + 2, \dots, m\}$.

Now we assume that the second fundamental form σ is parallel, that is, $\bar{\nabla}\sigma = 0$. Then we have from the above formulae that the tensor field P_{BA}

is written as

$$\begin{aligned}
 (P_{BA}) &= \begin{pmatrix} P_{ji} & P_{ji^*} & P_{ja} & P_{ja^*} & P_{jr} & P_{jr^*} \\ P_{j^*i} & P_{j^*i^*} & P_{j^*a} & P_{j^*a^*} & P_{j^*r} & P_{j^*r^*} \\ P_{bi} & P_{bi^*} & P_{ba} & P_{ba^*} & P_{br} & P_{br^*} \\ P_{b^*i} & P_{b^*i^*} & P_{b^*a} & P_{b^*a^*} & P_{b^*r} & P_{b^*r^*} \\ P_{ri} & P_{ri^*} & P_{ra} & P_{ra^*} & P_{sr} & P_{sr^*} \\ P_{s^*i} & P_{s^*i^*} & P_{s^*a} & P_{s^*a^*} & P_{s^*r} & P_{s^*r^*} \end{pmatrix} \\
 &= \begin{pmatrix} \alpha\delta_{ji} & 0 & 0 & 0 & 0 & 0 \\ 0 & \alpha\delta_{ji} & 0 & 0 & 0 & 0 \\ 0 & 0 & P_{ba} & 0 & 0 & 0 \\ 0 & 0 & 0 & P_{b^*a^*} & P_{b^*r} & P_{b^*r^*} \\ 0 & 0 & 0 & P_{sa^*} & P_{sr} & P_{sr^*} \\ 0 & 0 & 0 & P_{s^*a^*} & P_{s^*r} & P_{s^*r} \end{pmatrix}. \tag{4.1}
 \end{aligned}$$

for $p, q \geq 1$ and a certain function α . Thus we have

Theorem 4.1. *In the first type warped product semi-slant submanifold M with parallel second fundamental form σ of an l.c.K.-space form $\tilde{M}(c)$, if p and q are bigger than 1, then the tensor field P_{BA} is written by (4.1).*

5. NORMALLY FLAT WARPED PRODUCT SEMI-SLANT SUBMANIFOLDS

Finally, we calculate the Ricci equation in a warped product semi-slant submanifold in an l.c.K.-space form.

By virtue of (1.1), we can separate the Riemannian curvature tensor $\tilde{R}(U, V, W, Z)$ for $U, V, W, Z \in \tilde{TM}$ as

$$\begin{aligned}
 2\tilde{R}(X_1, X_2, FZ_1, FZ_2) &= -c\tilde{g}(TX_1, X_2)\tilde{g}(JFZ_1, Z_2) \\
 &\quad + P(JX_1, X_2)\tilde{g}(JFZ_1, FZ_2) + P(JFZ_1, FZ_2)\tilde{g}(JX_1, X_2), \\
 2\tilde{R}(X_1, X_2, FZ_1, \xi) &= P(JFZ_1, \xi_1)\tilde{g}(JX_1, X_2), \\
 2\tilde{R}(X_1, X_2, \xi_1, \xi_2) &= -c\tilde{g}(JX_1, X_2)\tilde{g}(J\xi_1, \xi_2) \\
 &\quad + P(JX_1, X_2)\tilde{b}(J\xi_1, \xi_2) + P(J\xi_1, \xi_2)\tilde{g}(JX_1, X_2), \\
 4\tilde{R}(X_1, Z_1, FZ_2, FZ_3) &= -P(JX_1, FZ_3)\tilde{g}(FZ_1, FZ_2) \\
 &\quad + P(JX_1, FZ_2)\tilde{g}(FZ_1, FZ_3) + 2P(JX_1, Z_1)\tilde{g}(JFZ_2, FZ_3), \\
 4\tilde{R}(X_1, Z_1, FZ_2, \xi_1) &= -P(JX_1, \xi_1)\tilde{g}(FZ_1, FZ_2), \\
 2\tilde{R}(X_1, Z_1, \xi_1, \xi_2) &= P(JX_1, Z_1)\tilde{g}(J\xi_1, \xi_2), \\
 4\tilde{R}(Z_1, Z_2, FZ_3, FZ_4) &= c\{\tilde{g}(FZ_1, FZ_4)\tilde{g}(FZ_1, FZ_3) \\
 &\quad - \tilde{g}(FZ_1, FZ_4)\tilde{g}(FZ_1, FZ_3) - 2\tilde{g}(TZ_1, Z_2)\tilde{g}(JFZ_3, FZ_4)\} \\
 &\quad - P(JZ_1, FZ_4)\tilde{g}(FZ_2, FZ_3) + P(JZ_1, FZ_3)\tilde{g}(FZ_2, FZ_4)
 \end{aligned}$$

$$\begin{aligned}
& -P(JZ_2, FZ_3)\tilde{g}(FZ_1, FZ_4) + P(JZ_2, FZ_4)\tilde{g}(FZ_1, FZ_3) \\
& + 2\{P(JZ_1, Z_2)\tilde{g}(JFZ_3, FZ_4) + P(JFZ_3, FZ_4)\tilde{g}(JZ_1, Z_2)\}, \\
4\tilde{R}(Z_1, Z_2, FZ_3, \xi_1) & = -P(JZ_1, \xi)\tilde{g}(FZ_2, FZ_3) \\
& + P(JZ_2, \xi_1)\tilde{g}(FZ_1, FZ_3) + 2P(JFZ_3, \xi_1)\tilde{g}(JZ_1, Z_2), \\
2\tilde{R}(Z_1, Z_2, \xi_1, \xi_2) & = -c\tilde{g}(JZ_1, Z_2)\tilde{g}(J\xi_1, \xi_2) \\
& + P(JZ_1, Z_2)\tilde{g}(J\xi_1, \xi_2) + P(J\xi_1, \xi_2)\tilde{g}(JZ_1, Z_2)
\end{aligned}$$

for any $X_1, X_2 \in \mathcal{D}$, $Z_1, Z_2, Z_3, Z_4 \in \mathcal{D}^\theta$ and $\xi_1, \xi_2 \in \nu$. Hence we get from (2.2) that the Ricci equation is separated by

$$\begin{aligned}
2R^\perp(X_1, X_2, FZ_1, FZ_2) & - 2\tilde{g}([A_{FZ_1}, A_{FZ_2}]X_1, X_2) = \\
& -c\tilde{g}(JX_1, X_2)\tilde{g}(JFZ_1, FZ_2) + P(JX_1, X_2)\tilde{g}(JFZ_1, FZ_2) \\
& + P(JFZ_1, FZ_2)\tilde{g}(JX_1, X_2), \\
2R^\perp(X_1, X_2, FZ_1, \xi_1) & - 2\tilde{g}([A_{FZ_1}, A_{\xi_1}]X_1, X_2) = P(JFZ_1, \xi)\tilde{g}(JX_1, X_2), \\
2R^\perp(X_1, X_2, \xi_1, \xi_2) & - 2\tilde{g}([A_{\xi_1}, A_{\xi_2}]X_1, X_2) = -c\tilde{g}(JX_1, X_2)\tilde{g}(J\xi_1, \xi_2) + \\
& + P(JX_1, X_2)\tilde{g}(J\xi_1, \xi_2) + P(J\xi_1, \xi_2)\tilde{g}(JX_1, X_2), \\
4R^\perp(X_1, Z_1, FZ_2, FZ_3) & - 4\tilde{g}([A_{FZ_2}, A_{FZ_3}]X_1, Z_2) = \\
& = -P(JX_1, FZ_3)\tilde{g}(FZ_1, FZ_2) + P(JX_1, FZ_2)\tilde{g}(FZ_1, FZ_3) + \\
& + 2P(JX_1, Z_1)\tilde{g}(JFZ_2, FZ_3), \\
4R^\perp(X_1, Z_1, FZ_2, \xi) & - 4\tilde{g}([A_{FZ_2}, A_{\xi}]X_1, Z_1) = -P(JX_1, \xi)\tilde{g}(FZ_1, FZ_2), \\
2R^\perp(X_1, Z_1, \xi_1, \xi_2) & - 2\tilde{g}([A_{\xi_1}, A_{\xi_2}]X_1, Z_1) = P(JX_1, Z_1)\tilde{g}(J\xi_1, \xi_2), \\
4R^\perp(Z_1, Z_2, FZ_3, FZ_4) & - 4\tilde{g}([A_{FZ_3}, A_{FZ_4}]Z_1, Z_2) = \\
& = c\{\tilde{g}(FZ_1, FZ_4)\tilde{g}(FZ_2, FZ_3) - \tilde{g}(FZ_1, FZ_3)\tilde{g}(FZ_2, FZ_4) - \\
& - 2\tilde{g}(TZ_1, Z_2)\tilde{g}(JFZ_3, FZ_4)\} - P(JZ_1, FZ_4)\tilde{g}(FZ_2, FZ_3) + \\
& + P(JZ_1, FZ_3)\tilde{g}(FZ_2, FZ_4) - P(JZ_2, FZ_3)\tilde{g}(FZ_1, FZ_4) + \\
& + P(JZ_2, FZ_4)\tilde{g}(FZ_1, FZ_3) + 2\{P(JZ_1, Z_2)\tilde{g}(JFZ_3, FZ_4) + \\
& + P(JFZ_3, FZ_4)\tilde{g}(TZ_1, Z_2)\}, \\
4R^\perp(Z_1, Z_2, FZ_3, \xi_1) & - 4\tilde{g}([A_{FZ_3}, A_{\xi_1}]Z_1, Z_2) = 2P(JFZ_3, \xi_1)\tilde{g}(TZ_1, Z_2) - \\
& - P(JZ_1, \xi_1)\tilde{g}(FZ_2, FZ_3) + P(JZ_2, \xi)\tilde{g}(FZ_1, FZ_3), \\
4R^\perp(Z_1, Z_2, \xi_1, \xi_2) & - 2\tilde{g}([A_{\xi_1}, A_{\xi_2}]Z_1, Z_2) = -c\tilde{g}(JZ_1, Z_2)\tilde{g}(J\xi_1, \xi_2) + \\
& + P(JZ_1, Z_2)\tilde{g}(J\xi_1, \xi_2) + P(J\xi_1, \xi_2)\tilde{g}(JZ_1, Z_2)
\end{aligned}$$

for any $X_1, X_2 \in \mathcal{D}$, $Z_1, Z_2, Z_3, Z_4 \in \mathcal{D}^\theta$ and $\xi_1, \xi_2 \in \nu$.

Using the above equation, we have, for a generalized adopted frame, the following:

$$\begin{aligned}
2R^{\perp}_{jib^*a^*} - 2\tilde{g}([A_{b^*}, A_{a^*}]e_j, e_i) &= -c\tilde{g}(Je_j, e_i)\tilde{g}(Je_{b^*}, e_{a^*}) + \\
&\quad + P(Je_j, e_i)\tilde{g}(Je_{b^*}, e_{a^*}) + P(Je_{b^*}, e_{a^*})\tilde{g}(Je_j, e_i), \\
2R^{\perp}_{jia^*r} - 2\tilde{g}([A_{a^*}, A_r]e_j, e_i) &= P(Je_{a^*}, e_r)\tilde{g}(Je_j, e_i), \\
2R^{\perp}_{jisr} - 2\tilde{g}([A_{e_s}, A_{e_r}]e_j, e_i) &= -c\tilde{g}(Je_j, e_i)\tilde{g}(Je_s, e_r) + \\
&\quad + P(Je_j, e_i)\tilde{g}(Je_s, e_r) + P(Je_s, e_r)\tilde{g}(Je_j, e_i), \\
4R^{\perp}_{icb^*a^*} - 4\tilde{g}([A_{b^*}, A_{a^*}]e_i, e_c) &= \|Fe_c\|\{-P(Je_i, e_{a^*})\delta_{cb} + \\
&\quad + P(Je_i, e_{b^*})\delta_{ca}\} + 2P(Je_i, e_c)\tilde{g}(Je_{b^*}, e_{a^*}), \\
4R^{\perp}_{iba^*r} - 4\tilde{g}([A_{a^*}, A_r]e_i, e_b) &= -\|Fe_b\|P(Je_i, e_r)\delta_{ba}, \\
2R^{\perp}_{iasr} - 2\tilde{g}([A_s, A_r]e_i, e_a) &= P(Je_i, e_a)\tilde{g}(Je_s, e_r), \tag{5.1} \\
4R^{\perp}_{dcb^*a^*} - 4\tilde{g}([A_{b^*}, A_{a^*}]e_d, e_c) &= \\
&= c\{\|Fe_c\|\|Fe_d\|(\delta_{da}\delta_{cb} - \delta_{db}\delta_{ca}) - 2\tilde{g}(Te_d, e_c)\tilde{g}(Je_{b^*}, e_{a^*})\} - \\
&\quad - \|Fe_c\|\{P(Je_d, e_{a^*})\delta_{cb} - P(Je_d, e_{b^*})\delta_{ca}\} - \\
&\quad - \|Fe_d\|\{P(e_c^*, e_{b^*})\delta_{da} - P(Je_c, e_{a^*})\delta_{cb}\} + \\
&\quad + 2\{\|Fe_c\|P(Je_d, e_c)\tilde{g}(Je_{b^*}, e_{a^*}) + P(Je_{b^*}, e_{a^*})\tilde{g}(Te_d, e_c)\}, \\
4R^{\perp}_{cba^*r} - 4\tilde{g}([A_{a^*}, A_r]e_c, e_b) &= 2P(Je_{a^*}, e_r)\tilde{g}(Te_c, e_b) + \\
&\quad + \|Fe_c\|\|Fe_b\|\{P(Je_{b^*}, e_r)\delta_{ca} - P(Je_{c^*}, e_r)\delta_{ba}\}, \\
2R^{\perp}_{basr} - 2\tilde{g}([A_s, A_r]e_b, e_a) &= -c\tilde{g}(Te_b, e_a)\tilde{g}(Je_r, e_s) + \\
&\quad + P(Je_b, e_a)\tilde{g}(Je_s, e_r) + P(Je_s, e_r)\tilde{g}(Te_b, e_a),
\end{aligned}$$

where $Fe_a = \|Fe_a\|a^*$, $j, i \in \{1, 2, \dots, 2p\}$, $d, c, b, a \in \{2p+1, 2p+2, 2p+q\}$, and $s, r \in \{n+q, n+q+1, \dots, m\}$. By virtue of (2.5), we can formally put

$$\begin{aligned}
Je_j &= \sum_{i=1}^p (T_j^i e_i + T_j^{p+i} e_{p+i}) + T_j^a e_a + F_j^a e_a^* + F_j^s e_s, \\
Je_{p+j} &= \sum_{i=1}^p (T_{p+j}^i e_i + T_{p+j}^{p+i} e_{p+i}) + T_{p+j}^a e_a + F_{p+j}^a e_a^* + F_{p+j}^s e_s, \\
Je_a &= \sum_{i=1}^p (T_a^i e_i + T_a^{p+i} e_{p+i}) + T_a^c e_c + F_a^c e_c^* + F_a^s e_s, \\
Je_{a^*} &= \sum_{i=1}^p (t_a^i e_i + t_a^{p+i} e_{p+i}) + t_a^c e_c + f_a^c e_c^* + f_a^s e_s,
\end{aligned}$$

$$Je_s = \sum_{i=1}^p (t_s^i e_i + t_s^{p+i} e_{p+i}) + t_s^a e_a + f_s^a e_a^* + f_s^r e_r,$$

for $a, c \in \{2p+1, 2p+2, \dots, 2p+q\}$, $s, r \in \{n+q+1, n+q+2, \dots, m\}$, and $j \in \{1, 2, \dots, p\}$. Since, our frame is a generalized adapted one, we know in the above equation

$$\begin{pmatrix} T_j^i & T_{p+j}^i & T_a^i \\ T_j^{p+i} & T_{p+j}^{p+i} & T_a^{p+i} \\ T_j^a & T_{p+j}^a & T_b^a \end{pmatrix} = \begin{pmatrix} 0 & -\delta_j^i & 0 \\ \delta_j^i & 0 & 0 \\ 0 & 0 & T_b^a \end{pmatrix}, \quad (5.2)$$

$$\begin{pmatrix} F_j^a & F_j^s \\ F_{p+j}^a & F_{p+j}^s \\ F_b^a & F_b^s \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \\ F_b^a & 0 \end{pmatrix}, \quad (5.3)$$

$$\begin{pmatrix} t_a^i & t_a^{p+i} & t_a^c \\ t_s^i & t_s^{p+i} & t_s^a \end{pmatrix} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \quad (5.4)$$

and

$$\begin{pmatrix} f_a^c & f_a^s \\ f_s^a & f_s^r \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & f_s^r \end{pmatrix}. \quad (5.5)$$

From (5.5), we can easily get that $f_{ba} = 0$ identically.

Theorem 5.1. *With respect to the generalized adapted frame, the tensor field T, F, t and f satisfy (5.2), (5.3), (5.4) and (5.5), respectively.*

Thus due to (5.3), (5.4) and (5.5) the system of equations (5.1) can be written as follows:

$$\begin{aligned} 2R_{jib^*a^*}^\perp - 2\tilde{g}([A_{b^*}, A_{a^*}]e_j, e_i) &= 0, \\ R_{jia^*r}^\perp - \tilde{g}([A_{a^*}, A_r]e_j, e_i) &= 0, \\ R_{jisr}^\perp - \tilde{g}([A_s, A_r]e_j, e_i) &= 0, \\ 4R_{icb^*a^*}^\perp - 4\tilde{g}([A_{b^*}, A_{a^*}]e_i, e_c) &= \|Fe_c\| (P_{i^*a^*}\delta_{cb} - P_{i^*b^*}\delta_{ca}), \\ 4R_{iba^*r}^\perp - 4\tilde{g}([A_{a^*}, A_r]e_i, e_b) &= \|Fe_b\| P_{i^*r}\delta_{ba}, \\ 2R_{iasr}^\perp - 2\tilde{g}([A_s, A_r]e_i, e_a) &= -P_{i^*a}\tilde{g}(Je_s, e_r), \\ 4R_{dcb^*a^*}^\perp - 4\tilde{g}([A_{b^*}, A_{a^*}]e_d, e_c) &= c\|Fe_c\|\|Fe_d\|(\delta_{da}\delta_{cb} - \delta_{db}\delta_{ca}) + \\ &+ \|Fe_c\|\{(T_d^e P_{ea^*} + F_d^e P_{e^*a^*})\delta_{cb} - (T_d^e P_{eb^*} + F_d^e P_{e^*b^*})\delta_{ca}\} - \\ &- \|Fe_d\|\{P_{c^*b^*}\delta_{da} - (T_c^e P_{ea^*} + F_c^e P_{e^*a^*})\delta_{cb}\}, \\ 4R_{cba^*r}^\perp - 4\tilde{g}([A_{a^*}, A_r]e_c, e_b) &= 0, \\ 2R_{basr}^\perp - 2\tilde{g}([A_s, A_r]e_b, e_a) &= -cT_{ba}\tilde{g}(Je_r, e_s) + F_b^e P_{e^*a}\tilde{g}(Je_s, e_r) + \\ &+ P(Je_s, e_r)T_{ba}, \end{aligned}$$

for $j, i \in \{1, 2, \dots, p\}$, $d, c, b, a \in \{2p + 1, 2p + 2, \dots, 2p + q = n\}$ and $s, r \in \{n + q, n + q + 1, \dots, m\}$. Thus we have

Theorem 5.2. *If the first type warped product semi-slant submanifold in an l.c.K.-space form $M(c)$ is normally flat, that is, $R^\perp = 0$, identically, then the shape operators A_λ satisfy*

$$\tilde{g}([A_{b^*}, A_{a^*}]e_j, e_i) = 0,$$

$$\tilde{g}([A_{a^*}, A_r]e_j, e_i) = 0,$$

$$\tilde{g}([A_s, A_r]e_j, e_i) = 0,$$

$$4\tilde{g}([A_{b^*}, A_{a^*}]e_i, e_c) = -\|F e_c\| (P_{i^*a^*}\delta_{cb} - P_{i^*b^*}\delta_{ca}),$$

$$4\tilde{g}([A_{a^*}, A_r]e_i, e_b) = -\|F e_b\| P_{i^*r}\delta_{ba},$$

$$2\tilde{g}([A_s, A_r]e_i, e_a) = P_{i^*a}\tilde{g}(J e_s, e_r),$$

$$4\tilde{g}([A_{b^*}, A_{a^*}]e_d, e_c) = -c\|F e_c\|\|F e_d\|(\delta_{da}\delta_{cb} - \delta_{db}\delta_{ca}) + \\ + \|F e_c\|\{(T_d^e P_{ea^*} + F_d^e P_{e^*a^*})\delta_{cb} - (T_d^e P_{eb^*} + F_d^e P_{e^*b^*})\delta_{ca}\} - \\ - \|F e_d\|\{P_{c^*b^*}\delta_{da} - (T_c^e P_{ea^*} + F_c^e P_{e^*a^*})\delta_{cb}\},$$

$$\tilde{g}([A_{a^*}, A_r]e_c, e_b) = 0,$$

$$2\tilde{g}([A_s, A_r]e_b, e_a) = cT_{ba}\tilde{g}(J e_r, e_s) - F_b^e P_{e^*a}\tilde{g}(J e_s, e_r) - P(J e_s, e_r)T_{ba},$$

for $j, i \in \{1, 2, \dots, p\}$, $d, c, b, a \in \{2p + 1, 2p + 2, \dots, 2p + q = n\}$ and $s, r \in \{n + q, n + q + 1, \dots, m\}$.

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