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1, 2, 2  
1  
2

$X_1, Y_1, Z_1,$

[1, 2],

[3 – 10],

[11 – 15].

[10].

1 2

[7 – 9]. « »

$Q \sin \omega t$

$\omega.$

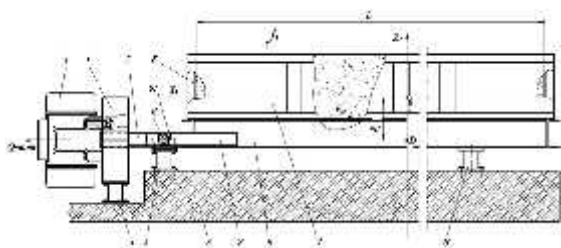
[3 – 4, 10].

$$(m_1 + m_2 + m_{pr1}) \frac{d^2 x_1}{dt^2} + b_3 \frac{dx_1}{dt} + c_3 x_1 + f(t) = Q \sin \omega t \quad (1)$$

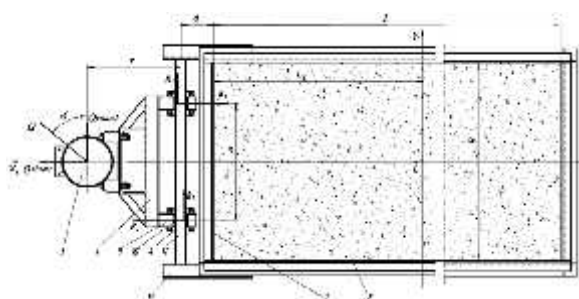
$$f(t) = \pm F_{tr}; \quad (2)$$

$$F_{tr} = m_b g f_{tr} = \rho S_1 H g f_{tr}. \quad (3)$$

$m_b$  - ;  
 $f_{tr}$  - ;  
 $\rho$  - ;  
 $S_1$  - ;  
 $H$  - ;  
 $g$  -



1. « - »



2. « - »

$f(t)$  :

$$f(t) = \begin{cases} -F_{tr} & \text{ï ðè } -\pi \leq \omega t \leq 0, \\ F_{tr} & \text{ï ðè } 0 \leq \omega t \leq \pi. \end{cases} \quad (4)$$

$$f(t) = \frac{a_0}{2} + \sum_{k=1}^{\infty} (a_k \cos k\omega t + b_k \sin k\omega t), \quad (5)$$

$a_0, a_k, b_k$  - [6, 7].  
 $[6]$   
 $a_0, a_k, b_k$ ,  
 $f(t)$

$$f(t) = \frac{4F_{tr}}{\pi} \left\{ \begin{aligned} & \sin \omega t + \frac{\sin 3\omega t}{3} + \frac{\sin 5\omega t}{5} + \dots \\ & + \frac{\sin[(2n\omega + 1)t]}{2n + 1} \end{aligned} \right\}. \quad (6)$$

$m_{pr1}$  [13]:

$$m_{pr1} = \frac{\rho S_2 (1 - \cos kl)}{2k \sin kl}, \quad (7)$$

$S_2 = B \cdot H$ ;  $l = L_{\hat{a}}$ ,  
 $l = L_{\hat{a}}$ ;  $k = \dots$ ;  $E = \dots$

$$L_{\hat{a}} = \frac{2\pi}{\omega} \sqrt{\frac{E}{\rho}}. \quad (8)$$

$X_1$ :

$$(m_1 + m_2 + m_{pr1}) \frac{d^2 x_1}{dt^2} + b_3 \frac{dx_1}{dt} + c_3 x_1 = \left( Q - \frac{4F_{tr}}{\pi} \right) \sin \omega t - \frac{4F_{tr}}{\pi} \left\{ \frac{\sin 3\omega t}{3} + \frac{\sin 5\omega t}{5} + \dots + \frac{\sin[(2n\omega + 1)t]}{2n + 1} \right\} \quad (9)$$

(6), (2)

$$x_1(t) = A_{11} \sin(\omega t - \phi_{11}) - A_{13} \sin(3\omega t - \phi_{13}) - A_{15} \sin(5\omega t - \phi_{15}), \quad (10)$$

$A_{11}, A_{13}, A_{15}$  -

$X_1$

$$A_{11} = \frac{Q - \frac{4F_{tr}}{\pi}}{(m_1 + m_2 + m_{pr1}) \sqrt{(p_{011}^2 - \omega^2)^2 + 4\delta_{11}^2 \omega^2}}; \quad (11)$$

$$A_{13} = \frac{\frac{4F_{tr}}{\pi}}{(m_1 + m_2 + m_{pr1}) \sqrt{(p_{011}^2 - 9\omega^2)^2 + 36\delta_{11}^2 \omega^2}}; \quad (12)$$

$$A_{15} = \frac{\frac{4F_{tr}}{\pi}}{(m_1 + m_2 + m_{pr1}) \times \sqrt{(p_{011}^2 - 25\omega^2)^2 + 100\delta_{11}^2 \omega^2}}, \quad (13)$$

$\phi_{11}, \phi_{13}, \phi_{15}$  -

$X_1$

$Q$ ;

$p_{011}$  -

$X$ ;

$\delta_{11}$  -

$X$ ;

$$p_{011} = \sqrt{\frac{c_3}{m_1 + m_2 + m_{pr1}}}; \quad (14)$$

$$\delta_{11} = \frac{b_3}{2(m_1 + m_2 + m_{pr1})}$$

$$\phi_{11} = \arctg \frac{2\delta_{11}\omega}{p_{011} - \omega}; \quad (15)$$

$$\phi_{13} = \arctg \frac{6\delta_{11}\omega}{p_{011} - 9\omega^2}; \quad (16)$$

$$\phi_{15} = \arctg \frac{10\delta_{11}\omega}{p_{011} - 25\omega^2}. \quad (17)$$

$Y_1$

$$(J_y + J_{pr1}) \frac{d^2 \psi_{y1}}{dt^2} + n_2 \frac{d\psi_{y1}}{dt} + k_2 \psi_{y1} = Q \frac{m_2}{m_1 + m_2} z_{c1} \sin \omega t \quad (18)$$

$J_{pr1}$  -

$Y_1$ :

$$J_{pr1} = \frac{m_{pr2}(L^2 + H^2)}{12} + m_{pr2}(L - L_2)^2; \quad (19)$$

$L_2$  -

$m_{pr2}$  -

$z_{c1}$  -

$Q \sin \omega t$ .

$m_{pr2}$

[13]:

$$m_{i\delta 2} = \frac{\rho S_1}{k} \text{tgkH}. \quad (20)$$

(18),

$$\psi_{y1}(t) = \Psi_{y1} \sin(\omega t - \xi_{11}); \quad (21)$$

$\Psi_{y1}$  -

$Y_1$ ;

$Z_1$  -

$$\Psi_{y1} = \frac{Q \frac{m_2}{m_1 + m_2} z_{c1}}{(J_y + J_{pr1}) \sqrt{(p_{031}^2 - \omega^2)^2 + 4\delta_{31}^2 \omega^2}}; \quad (22)$$

$p_{031}$  -

$Y_1$ ;

$$p_{031} = \sqrt{\frac{k_2}{J_y + J_{pr1}}}; \quad (23)$$

$\delta_{31}$  -

$$Y_1 ;$$

$$\delta_{31} = \frac{n_2}{2(J_y + J_{pr1})} ; \quad (24)$$

$$\xi_{11} = \arctg \frac{2\delta_{31}\omega}{p_{031}^2 - \omega^2} . \quad (25)$$

$Y_1 :$

$$(m_2 + m_{pr3}) \frac{d^2 y_1}{dt^2} + b_2 \frac{dy_1}{dt} + c_2 y_1 =$$

$$2Q \frac{r}{a} \mu \cos \omega t - \frac{4F_{tr}}{\pi} \times$$

$$\left\{ \frac{\sin \omega t}{1} + \frac{\sin 3\omega t}{3} + \frac{\sin 5\omega t}{5} + \dots + \frac{\sin[(2n\omega + 1)t]}{2n + 1} \right\}$$

$m_{pr3} -$

$Y_1 :$

$$m_{pr3} = \frac{\rho S_3 (1 - \cos k B_1)}{2k \sin k B_1} , \quad (27)$$

$S_3 -$

$S_3 = L \cdot h ;$

$B_1 -$

$B_1 ,$

$B_1 = L \hat{a} ,$

$, B_1 = B .$

$$(6), \quad (26),$$

$(26)$

$$y_1(t) = A_{20} \cos(\omega t + \phi_{21}) -$$

$$-A_{21} \sin(\omega t - \phi_{21}) - A_{23} \sin(3\omega t - \phi_{23}) - , (28)$$

$$-A_{25} \sin(5\omega t - \phi_{25})$$

$A_{20}, A_{21}, A_{23}, A_{25} -$

$Y_1 ;$

$\phi_{21}, \phi_{23}, \phi_{25} -$

$Y_1$

;

$$A_{20} = \frac{2Q \frac{r}{a} \mu}{(m_2 + m_{pr3}) \sqrt{(p_{021}^2 - \omega^2)^2 + 4\delta_{21}^2 \omega^2}} ; \quad (29)$$

$p_{021} -$

$Y_1 ;$

$\delta_{21} -$

$Y_1 ;$

$$p_{021} = \sqrt{\frac{c_2}{m_2 + m_{pr3}}} ; \quad (30)$$

$$\delta_{21} = \frac{b_2}{2(m_2 + m_{pr3})} ;$$

$$\phi_{21} = \arctg \frac{2\delta_{21}\omega}{p_{021}^2 - \omega^2} . \quad (31)$$

$$A_{11} = \frac{\frac{4F_{tr}}{\pi}}{(m_2 + m_{pr3}) \sqrt{(p_{021}^2 - \omega^2)^2 + 4\delta_{21}^2 \omega^2}} ; \quad (32)$$

$$A_{13} = \frac{\frac{4F_{tr}}{\pi}}{(m_2 + m_{pr3}) \sqrt{(p_{021}^2 - 9\omega^2)^2 + 36\delta_{21}^2 \omega^2}} ; \quad (33)$$

$$A_{15} = \frac{\frac{4F_{tr}}{\pi}}{(m_2 + m_{pr3}) \sqrt{(p_{021}^2 - 25\omega^2)^2 + 100\delta_{21}^2 \omega^2}} ; \quad (34)$$

$$\phi_{23} = \arctg \frac{6\delta_{21}\omega}{p_{021}^2 - 9\omega^2} ; \quad (35)$$

$$\phi_{25} = \arctg \frac{10\delta_{21}\omega}{p_{021}^2 - 25\omega^2} . \quad (36)$$

$Z_1$

$$2Q \frac{r}{a} \mu (d + L_2) \cos \omega t$$

:

$$(J_z + J_{pr3}) \frac{d^2 \psi_{z1}}{dt^2} + n_3 \frac{d\psi_{z1}}{dt} +$$

$$+ k_3 \psi_{z1} = Qr \frac{2}{a} \mu (d + L_1) \cos \omega t - , \quad (37)$$

$$- \frac{2F_{tr} L}{\pi} \left\{ \frac{\sin \omega t}{1} + \frac{\sin 3\omega t}{3} + \frac{\sin 5\omega t}{5} + \dots + \frac{\sin[(2n\omega + 1)t]}{2n + 1} \right\}$$

$J_{pr3} -$

:

$$J_{pr3} = \frac{m_{pr3}L^2}{12}. \quad (38)$$

(37)

$$\Psi_{z1}(t) = \Psi_{z10} \cos(\omega t + \xi_{21}) - \Psi_{z11} \sin(\omega t - \xi_{21}) - \Psi_{z13} \sin(3\omega t - \xi_{23}) - \Psi_{z15} \sin(5\omega t - \xi_{25}) \quad (39)$$

$\Psi_{z10}, \Psi_{z11}, \Psi_{z13}, \Psi_{z15}$  -

$Z_1$

$\xi_{21}, \xi_{23}, \xi_{25}$  -

$Z_1$

$$\Psi_{z10} = \frac{2Q \frac{r}{a} \mu (d + L_1)}{(J_z + J_{pr3}) \sqrt{(p_{041}^2 - \omega^2)^2 + 4\delta_{41}^2 \omega^2}}; \quad (40)$$

$$\Psi_{z11} = \frac{\frac{2F_{tr}L}{\pi}}{(J_z + J_{pr3}) \sqrt{(p_{041}^2 - \omega^2)^2 + 4\delta_{41}^2 \omega^2}}; \quad (41)$$

$$\Psi_{z13} = \frac{\frac{2F_{tr}L}{\pi}}{(J_z + J_{pr3}) \sqrt{(p_{041}^2 - 9\omega^2)^2 + 36\delta_{41}^2 \omega^2}}; \quad (42)$$

$$\Psi_{z15} = \frac{\frac{2F_{tr}L}{\pi}}{(J_z + J_{pr3}) \sqrt{(p_{041}^2 - 25\omega^2)^2 + 100\delta_{41}^2 \omega^2}}; \quad (43)$$

$$p_{041} = \sqrt{\frac{k_3}{J_z + J_{pr3}}}; \quad \delta_{41} = \frac{n_3}{2(J_z + J_{pr3})}; \quad (44)$$

$$\xi_{21} = \arctg \frac{2\delta_{41}\omega}{p_{041}^2 - \omega^2}; \quad (45)$$

$$\xi_{23} = \arctg \frac{6\delta_{41}\omega}{p_{041}^2 - 9\omega^2}; \quad (46)$$

$$\xi_{25} = \arctg \frac{10\delta_{41}\omega}{p_{041}^2 - 25\omega^2}. \quad (47)$$

$Z_1$

$Qr \cos \omega t$

:

$$(J_z + J_{pr4}) \frac{d^2 \Psi_{z2}}{dt^2} + n_3 \frac{d\Psi_{z2}}{dt} + k_3 \Psi_{z2} = Qr \cos \omega t - \quad (48)$$

$$- \frac{2F_{tr}B}{\pi} \left\{ \frac{\sin \omega t}{1} + \frac{\sin 3\omega t}{3} + \frac{\sin 5\omega t}{5} + \dots + \frac{\sin[(2n\omega + 1)t]}{2n + 1} \right\}$$

$J_{pr4}$  -

$$J_{pr4} = \frac{m_{pr3}B^2}{12}. \quad (49)$$

(2.95)

$$\Psi_{z2}(t) = \Psi_{z20} \cos(\omega t + \xi_{31}) - \Psi_{z21} \sin(\omega t - \xi_{31}) - \Psi_{z23} \sin(3\omega t - \xi_{33}) - \Psi_{z25} \sin(5\omega t - \xi_{35}) \quad (50)$$

$\Psi_{z20}, \Psi_{z21}, \Psi_{z23}, \Psi_{z25}$  -

$Z_1$

$\xi_{31}, \xi_{33}, \xi_{35}$  -

$Z_1$

$$\Psi_{z20} = \frac{Qr}{(J_z + J_{pr4}) \sqrt{(p_{051}^2 - \omega^2)^2 + 4\delta_{51}^2 \omega^2}}; \quad (51)$$

$$\Psi_{z21} = \frac{\frac{2F_{tr}B}{\pi}}{(J_z + J_{pr4}) \sqrt{(p_{051}^2 - \omega^2)^2 + 4\delta_{51}^2 \omega^2}}; \quad (52)$$

$$\Psi_{z23} = \frac{\frac{2F_{tr}B}{\pi}}{(J_z + J_{pr4}) \sqrt{(p_{051}^2 - 9\omega^2)^2 + 36\delta_{51}^2 \omega^2}}; \quad (53)$$

$$\Psi_{z25} = \frac{\frac{2F_{tr}B}{\pi}}{(J_z + J_{pr4}) \sqrt{(p_{051}^2 - 25\omega^2)^2 + 100\delta_{51}^2 \omega^2}}; \quad (54)$$

$$p_{051} = \sqrt{\frac{k_3}{J_z + J_{pr4}}}; \quad \delta_{51} = \frac{n_3}{2(J_z + J_{pr4})}; \quad (55)$$

$$\xi_{31} = \arctg \frac{2\delta_{51}\omega}{p_{051}^2 - \omega^2}; \quad (56)$$

$$\xi_{33} = \arctg \frac{6\delta_{51}\omega}{p_{051}^2 - 9\omega^2}; \quad (57)$$

$$\xi_{35} = \arctg \frac{10\delta_{51}\omega}{p_{051}^2 - 25\omega^2}. \quad (58)$$

$$\begin{aligned}
 X_{d1}(y, t) &= x_1(t) + y\Psi_{z2}(t) - z_{c1}\Psi_{y1}(t) = \\
 &= A_{11} \sin(\omega t - \phi_{11}) - A_{13} \sin(3\omega t - \phi_{13}) - \\
 &- A_{15} \sin(5\omega t - \phi_{15}) + y[\Psi_{z20} \cos(\omega t + \xi_{31}) - \\
 &- \Psi_{z21} \sin(\omega t - \xi_{31}) - \Psi_{z23} \sin(3\omega t - \xi_{33}) - \\
 &- \Psi_{z25} \sin(5\omega t - \xi_{35})] - z_{c1}\Psi_{y1} \sin(\omega t - \xi_{11}) \\
 &\quad \text{ï ðè} \quad -0,5B \leq y \leq 0,5B
 \end{aligned}
 \tag{59}$$

$$\begin{aligned}
 Y_{d1}(x, t) &= y_1(t) + x\Psi_{z1}(t) = A_{20} \cos(\omega t + \phi_{21}) - \\
 &- A_{21} \sin(\omega t - \phi_{21}) - A_{23} \sin(3\omega t - \phi_{23}) - \\
 &- A_{25} \sin(5\omega t - \phi_{25}) + x[\Psi_{z10} \cos(\omega t + \xi_{21}) - \\
 &- \Psi_{z11} \sin(\omega t - \xi_{21}) - \Psi_{z13} \sin(3\omega t - \xi_{23}) - \\
 &- \Psi_{z15} \sin(5\omega t - \xi_{25})] \\
 &\quad \text{ï ðè} \quad -(L - L_2) \leq x \leq L_2
 \end{aligned}
 \tag{60}$$

$$\begin{aligned}
 Z_{d1}(x, t) &= x\Psi_{y1}(t) = x\Psi_{y1} \sin(\omega t - \xi_{11}) \\
 &\quad \text{ï ðè} \quad -(L - L_2) \leq x \leq L_2
 \end{aligned}
 \tag{61}$$

$$\begin{aligned}
 X_{d1}(y, t) &= M_{11} \sin(\omega t - \theta_{11}) - \\
 &- A_{13} \sin(3\omega t - \phi_{13}) - A_{15} \sin(5\omega t - \phi_{15}) + \\
 &+ y[N_{11} \cos(\omega t + \theta_{12}) - \Psi_{z23} \sin(3\omega t - \xi_{33}) - \\
 &- \Psi_{z25} \sin(5\omega t - \xi_{35})] \quad \text{ï ðè} \quad -0,5B \leq y \leq 0,5B
 \end{aligned}
 \tag{62}$$

$$M_{11} = \sqrt{A_{11}^2 - 2A_{11}z_{c1}\Psi_{y1} \cos(\phi_{11} - \xi_{11}) + z_{c1}^2\Psi_{y1}^2}; \tag{63}$$

$$N_{11} = \sqrt{\Psi_{z20}^2 + \Psi_{z21}^2 + 2\Psi_{z20}\Psi_{z21} \cos 2\xi_{31}}; \tag{64}$$

$$\theta_{11} = \text{arctg} \frac{A_{11} \sin \phi_{11} - z_{c1}\Psi_{y1} \sin \xi_{11}}{A_{11} \cos \phi_{11} - z_{c1}\Psi_{y1} \cos \xi_{11}}; \tag{65}$$

$$\theta_{12} = \text{arctg} \frac{\Psi_{z20} \sin \xi_{31} + \Psi_{z21} \cos \xi_{31}}{\Psi_{z20} \cos \xi_{31} + \Psi_{z21} \sin \xi_{31}}. \tag{66}$$

$$\begin{aligned}
 Y_{d1}(x, t) &= M_{21} \cos(\omega t + \theta_{21}) - \\
 &- A_{23} \sin(3\omega t - \phi_{23}) - A_{25} \sin(5\omega t - \phi_{25}) + \\
 &+ x[N_{21} \cos(\omega t + \theta_{22}) - \Psi_{z13} \sin(3\omega t - \xi_{23}) - \\
 &- \Psi_{z15} \sin(5\omega t - \xi_{25})] \\
 &\quad \text{ï ðè} \quad -(L - L_2) \leq x \leq L_2
 \end{aligned}
 \tag{67}$$

$$M_{21} = \sqrt{A_{20}^2 + A_{21}^2 + 2A_{20}A_{21} \cos 2\phi_{21}}; \tag{68}$$

$$N_{11} = \sqrt{\Psi_{z10}^2 + \Psi_{z11}^2 + 2\Psi_{z10}\Psi_{z11} \cos 2\xi_{21}}; \tag{69}$$

$$\theta_{21} = \text{arctg} \frac{A_{20} \sin \phi_{21} + A_{21} \cos \phi_{21}}{A_{20} \cos \phi_{21} + A_{21} \sin \phi_{21}}; \tag{70}$$

$$\theta_{22} = \text{arctg} \frac{\Psi_{z10} \sin \xi_{21} + \Psi_{z11} \cos \xi_{21}}{\Psi_{z10} \cos \xi_{21} + \Psi_{z11} \sin \xi_{21}}. \tag{71}$$

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**RESEARCH OF VIBRATIONS  
OF THE VIBRATION SETTING REINFORCED CONCRETE WARES**

.G. Maslov, M.P. Nesterenko, D.S. Ped

*Stage-by-stage consideration motion of the offered vibration setting is expounded in relation to co-ordinate axes, passing through the compatible center weight form and formed concrete good taking into account properties concrete mixture.*

**Keywords:** *vibration , concrete mix, resilient support.*