623.592:623.618:358.4

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[1].
[1, 2, 3],

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[4],

[5]

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[6]

[7].

(.1) [11].

. 1.

[11].

[7].

[8, 9]

(

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$$B = \bigcup_{i=1}^n b_i$$

[10].

$$b_i = \{x_{i1}, x_{i2}, \dots, x_{ik}\} \quad (1)$$

$$X = \bigcup_{j=1}^m X_j -$$

()

$$t^{x_j} -$$

$$t^{b_i} -$$

$$T_X = \bigcup_{j=1}^m t^{x_j} -$$

$$T_B = \bigcup_{i=1}^n t^{b_i} -$$

$$T = \langle T_X, T_B \rangle \quad (2)$$

$$X_t = \{x_{t_1}, x_{t_2}, \dots, x_{t_{k_t}}\} -$$

$$B_t = \{b_{t_1}, b_{t_2}, \dots, b_{t_{n_t}}\} -$$

$$t = \{x_{t_1}, x_{t_2}, \dots, x_{t_{k_t}}, b_{t_1}, b_{t_2}, \dots, b_{t_{n_t}}\}, \quad (3)$$

$k_t -$

$t, n_t -$

$t.$

0

1.

[12].

$$p = V \cdot H, \quad (4)$$

$V -$

$H -$

$$M_t = \langle X_t, B_t, H_t, V_{x_t}, V_{b_t}, R_t \rangle, \quad (5)$$

$$X_t = \{x_{t_1}, x_{t_2}, \dots, x_{t_{k_t}}\} -$$

$t;$

$$B_t = \{b_{t_1}, b_{t_2}, \dots, b_{t_{n_t}}\} -$$

$H_t -$

$t;$

$$\overline{V_{x_t}} = (V(x_{t_1}), V(x_{t_2}), \dots, V(x_{t_r})) -$$

$t;$

$$\overline{V_{B_t}} = (V(b_{t_1}), V(b_{t_2}), \dots, V(b_{t_n})) -$$

$$R_t = (r_1(t), r_2(t), \dots, r_k(t)) -$$

$t.$

$$Q_t = \langle \bar{t}, X_t, H_t, B_t, P_t, V_{x_t}, V_{b_t}, R_t \rangle, \quad (6)$$

$\bar{t} -$;
 $X_t -$,

$X(A) .$

$$\min_{\bar{t}, X(A) \subset X_t} r_i(\bar{t}) \quad i = 1, 2, \dots, k, \quad (8)$$

);

$H_t -$;
 $B_t -$ 0 1;

$$\min_{\bar{t}, C(A) \subset C_t} r_i(\bar{t}) : r_1(\bar{t}) \leq r_1, \dots, r_k(\bar{t}) \leq r_k, \quad i = 1, 2, \dots, k. \quad (9)$$

$P_t -$,

$V(A, \bar{t}) -$

$V_{x_t} -$;

$V_{b_t} -$, 0 1;

[12].

$R_t -$, 0 1;

$$\max_{\bar{t}, X(A) \subset X_t} V(A, \bar{t}), \quad (10)$$

$R_t -$,

$$\min_{\bar{t}, X(A) \subset X_t} V(A, \bar{t}) : r_1(\bar{t}) \leq r_1, \dots, r_k(\bar{t}) \leq r_k, \quad i = 1, 2, \dots, k \quad (11)$$

$R_t = (L, T, S):$

$L -$;
 100; $T -$,

$S -$;

G_t

$$G_t = \prod_{t=1}^n g_t, \quad (7)$$

$g_t -$;
 $t .$

. 2.

/	t	H	$\overline{V_{x_t}}$				$\overline{V_{B_t}}$				R		
			x_{t_1}	x_{t_2}	...	x_{t_r}	b_{t_1}	b_{t_2}	...	b_{t_n}	L	T	S
1	1	0,1	0	0,7		0,45	0,93	0,60		0,29	10	12	4
2	3	0,24	0,29	0,56	...	0,42	0,86	0,53	...	0,18	54	23	7
3	3	0,9	0,79	0,87	...	0,09	0,64	0,49	...	0,70	34	5	6
...	...	...	...	...	...	...	...	...	...	...	...	...	...
100	M	0,5	0,79	0,99	...	0,80	0,88	0,29	...	0,28	57	78	10

k

$\bar{t}$, k = const

$\max(F(A))$,

:

$$F(A) = \sum_{i=1}^k H_i + \sum_{i=1}^k V(x_{t_i}) + \sum_{i=1}^k L_i - \sum_{i=1}^k T_i - \sum_{i=1}^k S_i \quad (12)$$

:

$$\max(\sum_{i=1}^k L_i); \min \sum_{i=1}^k T_i; \min(\sum_{i=1}^k S_i); \max(\sum_{i=1}^k V(x_{t_i})).$$

(12).

10	0,0082	.
100	5,98	.
200	49,98	.

100

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METHOD OF FORMING SET INDIVIDUAL TEST TASKS FOR ASSESSMENT LEVEL OF OPERATOR TRAINING ACS DURING SIMULATOR TRAINING

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This paper proposes a method for generating a set of individual test items for testing automated operator. This method will allow mnogokriterialnoy based assessment form, the required set of tests to determine the level of training of operators ACS. The results obtained allow to control the operator's activity to develop strategies individual or group training with subsequent calculation of prediction learning. This will enable an individual approach to learning ACS operators with regard to their level of training.

Keywords: *combat control officer, simulator complexes, automated quality control system operator training ACS, formation of individual tests, training, operator.*