



$$y[n] = \sum_{k=1}^3 y_k[n] = \sum_{k=1}^3 U_k \cos(\Omega_k n + \varphi_k), \quad (2)$$
$$\Omega_k = 2\pi\omega_k / \omega_s = 2\pi T_s / T_k -$$
$$\omega_s = 2\pi f_s = 2\pi / T_s -$$
$$, [ \quad ].$$

$$0,095 \quad , 0,105 \quad , 0,106 \quad :$$
$$f_1 = 2533,33 \quad , f_2 = 2800,00 \quad ,$$
$$f_3 = 2826,67 \quad .$$

Matlab

Matlab,

1.

```
%=====
Fs = 1e6; % , 1
Ts = 1/Fs; % , [ ]
%=====
%
%-----
%
c = 300 * 1e6; % [ / ],
%
%-----
F0 = 92 * 1e9; % [ ],
F1 = 96 * 1e9; % [ ],
dF = F1 - F0; % [ ],
dt = 10 * 1e-4; % [c],
%-----
%
%-----
D = [0.030; 0.040; 0.041; 0.042] + 0.065;
% [ ],
%
t_del = D .* (2/c); % [ ],
%
F_beat = t_del .* (dF/dt); % [ ],
% (beat)
%
U_beat = [1.0; 1.0; 1.0; 0.0]; % [ / ],
%
%-----
%
%-----
N = floor(dt/Tdis); % [samples],
% dt
n = 0:N-1; % -
%-----
%
%-----
n=1:N ( ) F_beat ( ).
%-----
Phi0_beat = 2*pi*(F0 + 0.5*(dF/dt)*t_del).*t_del; % [ ],
% ( )
%
ddF= dF*1e-11; % [ ], ( )
%
Phi_Start = Phi0_beat*ones(1,N); %
```

```
( )
Phi_Line = 2*pi*F_beat*Tdis*n;
%
Phi_NLine_1=0*2*pi*ones(size(F_beat))*(ddF*((1/dt)*Tdis*n)*
Tdis.*n); % (
%
Phi_NLine_2= 0*2*pi*ones(size(F_beat))
*(ddF*sin(2*pi*(1/dt)*Tdis*n)*Tdis.*n);
% (
%
Phi_Total = Phi_Start + Phi_Line + Phi_NLine_1 +
Phi_NLine_2; %
%=====
%
%-----
% : Mode = fixed ( )
% : RoundMode
= floor ( , ,
, )
% : OverflowMode = saturate
( )
% : Format = [Nq Nq-1] ( Nq ,
Nq-1 )
%-----
Nq = 24; q = quantizer('Mode','fixed', 'RoundMode',
'floor','OverflowMode', 'saturate','Format',[Nq
Nq-1]);
%-----
SNR = 100; % / [ ]
%-----
Nacc=10000; % ,
L = 1000; % 1000 =
(=830
)
m = 1:L; %
s_acc_1 = zeros(size(m)); %
%-----
for acc_loop = 1:Nacc; %
%
frame = acc_loop;
%-----
s_clr = 1e4 * U_beat*cos(Phi_Total); %
% ( + )
%-----
Umax = max(abs(s_clr)); %
% ( )
s_mix = awgn(s_clr,SNR,'measured'); %
% / [ ]
% Umax = max(abs(s_mix)); %
% ( )
Unrm = Umax; %
%
s_nrm = 0.9 * s_mix / Unrm; %
%
% ( )
s_qnt = quantize(q,s_nrm); % s_fix =
fi(s_nrm,1,16,15);
s_acc_1 = s_acc_1 + s_qnt; %
%
end; % : for acc_loop
= 1:Nacc;
%-----
```

```

s_acc_1 = s_acc_1 ./ frame; %
% -----
%
% -----
s = s_acc_1; %
,
SNR
% =====
. 1.

```

. ( )

$$x_i[n]$$

$$r_{xx}[m] = E_i \left\{ x_i[n+m] x_i^*[n] \right\}, \quad (3)$$

$$P_{xx}(f) = T \sum_{m=-\infty}^{+\infty} r_{xx}[m] e^{-j2\pi f m T} \quad [ \quad / \quad ]. \quad (4)$$

$$\mathcal{D}_{xx}(f)$$

( )  $\hat{r}_{xx}[m]$   $\check{r}_{xx}[m]$

$m \in [-L; L], \quad N$

$x[n], \quad n \in [0; N-1], \quad L \leq N/10,$

$r_{xx}[m]:$

$$\hat{r}_{xx}[m] = \frac{1}{N-m} \sum_{n=0}^{N-m-1} x[n+m] x^*[n], \quad (5)$$

$$\mathcal{D}_{xx}(f) = T \sum_{m=-L}^L \check{r}_{xx}[m] e^{-j2\pi f m T}, \quad (6)$$

$$-\frac{1}{2T} \leq f \leq \frac{1}{2T}$$

$\mathcal{D}_{xx}(f)$  (3) :

$$\overline{\mathcal{D}_{xx}(f)} = T \sum_{m=-L}^L \overline{\hat{r}_{xx}[m]} e^{-j2\pi f m T} = T \sum_{m=-L}^L r_{xx}[m] e^{-j2\pi f m T} =$$

$$= T \sum_{m=-\infty}^{+\infty} w_R[m] r_{xx}[m] e^{-j2\pi f m T} = P_{xx}(f) \otimes W_R(f),$$

$$w_R[m] = \begin{cases} 1, & m \in [-L; L] \\ 0, & m \notin [-L; L] \end{cases},$$

$$P_{xx}(f) = F \{ r_{xx}[m] \}, \quad W_R(f) = F \{ w_R[m] \}.$$

$$w_R[m]$$

( )

:

$$W_R(f) = F \{ w_R[m] \} = D_L(f) = \frac{\sin(2L+1)\pi f T}{\sin \pi f T}.$$

$$\check{P}_{xx}(f)$$

$$w_T[m] = \begin{cases} 1-|m|/N, & m \in [-L; L] \\ 0, & m \notin [-L; L] \end{cases},$$

$$P_{xx}(f) = F \{ r_{xx}[m] \},$$

$$W_T(f) = F \{ w_T[m] \}.$$

$$w_T[m]$$

( ) :

$$W_T(f) = F \{ w_T[m] \} = \frac{2}{L} D_L^2(f) = \frac{2 \sin^2(L+1)\pi f T}{L \sin^2 \pi f T}$$

$$, \quad \overline{P_{xx}(f)} \quad \overline{\check{P}_{xx}(f)}$$

$$P_{xx}(f),$$

$$\overline{\mathcal{D}_{xx}(f)}$$

$$P_{xx}(f) \quad W_R(f)$$

$$w_R[m] \quad W_T(f)$$

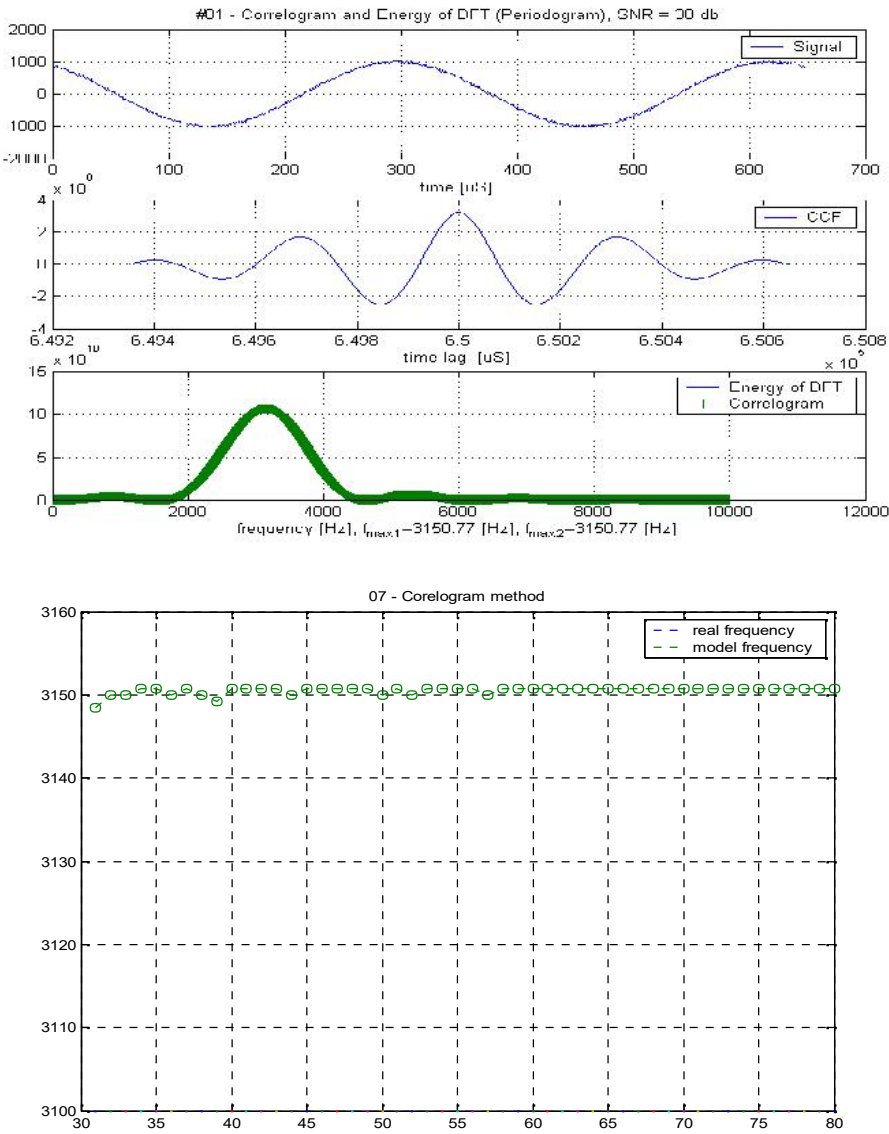
$$w_T[m].$$

$\mathcal{D}_{xx}(f)$  :

$$\text{var} \{ \mathcal{D}_{xx}(f) \} \cong \left( \frac{1}{N} \sum_{m=-L}^L w_R^2[m] \right) P_{xx}^2(f) = \frac{2L+1}{N} P_{xx}^2(f).$$

$$\check{P}_{xx}(f) :$$

$$\text{var} \{ \check{P}_{xx}(f) \} \cong \left( 1 + \left( \frac{\sin 2\pi f T N}{N \sin 2\pi f T} \right)^2 \right) P_{xx}^2(f).$$



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$$\tilde{P}_{xx}(f)$$

$$\tilde{P}_{xx}(f)$$

$$x_i[n]$$

$$\tilde{P}_{xx}(f)$$

$$P_{xx}(f) = \lim_{N \rightarrow \infty} E_i \left\{ \frac{\left| T \sum_{n=-N}^N x_i[n] e^{-j2\pi f n T} \right|^2}{(2N+1)T} \right\} \quad [ \quad / \quad ] \quad (7)$$

$$\tilde{P}_{xx}(f)$$

$$x_i[n],$$

$$\tilde{P}_{xx}(f) = \overline{\tilde{P}_{xx}(f)} = \overline{\tilde{P}_{xx}(f)},$$

$$\tilde{P}_{xx}(f) = \frac{\left| T \sum_{n=0}^{N-1} x_i[n] e^{-j2\pi f n T} \right|^2}{NT} = \frac{T}{N} \left| \sum_{n=0}^{N-1} x_i[n] e^{-j2\pi f n T} \right|^2 [ \quad / \quad ], \quad (8)$$

$$\tilde{P}_{xx}(f) = \overline{\tilde{P}_{xx}(f)} = T \sum_{m=-L}^L \tilde{r}_{xx}[m] e^{-j2\pi f m T} = T \sum_{m=-L}^L \left( 1 - \frac{|m|}{N} \right) r_{xx}[m] e^{-j2\pi f m T} =$$

$$= T \sum_{m=-\infty}^{+\infty} w_T[m] r_{xx}[m] e^{-j2\pi f m T} = P_{xx}(f) \otimes W_T(f)$$

$$w_T[m]=\begin{cases}1-|m|/N, m\in[-L;L] \\ 0, m\notin[-L;L]\end{cases},$$

$$P_{xx}(f)=F\left\{r_{xx}[m]\right\},$$

$$W_T(f)=F\left\{w_T[m]\right\}.$$

$$w_T[m]$$

$$W_T(f)=F\left\{w_T[m]\right\}=\frac{2}{L}D_L^2(f)=\frac{2}{L}\frac{\sin^2(L+1)\pi fT}{\sin^2\pi fT}.$$

$$\overline{P_{xx}(f)}$$

$$P_{xx}(f),$$

$$\overline{\tilde{P}_{xx}(f)},\quad \overline{\tilde{P}_{xx}(f)}$$

$$P_{xx}(f)\quad W_T(f)$$

$$w_T[m].$$

$$\tilde{P}_{xx}(f)\quad (21),$$

$$\tilde{P}_{xx}(f),$$

$$\text{var}\left\{\tilde{P}_{xx}(f)\right\}=\text{var}\left\{\tilde{P}_{xx}(f)\right\}$$

$$\text{var}\left\{\tilde{P}_{xx}(f)\right\}\cong\left(1+\left(\frac{\sin2\pi fTN}{N\sin2\pi fT}\right)^2\right)P_{xx}^2(f).$$

$$,$$

$$.$$

$$.$$

$$P_{xx}(f)$$

$$f_k=k/KT,\quad 0\leq k\leq K-1,$$

$$,$$

$$(\quad),$$

$$(\quad)$$

$$:$$

$$\mathcal{D}_D[f_i]=\frac{1}{2P+1}\sum_{n=i-P}^{i+P}\tilde{P}_{xx}[f_n].\quad (9)$$

$$.$$

$$\mathcal{D}_D(f_i)=\tilde{P}_{xx}(f)\otimes H(f).$$

$$,$$

$$x[n]\quad N$$

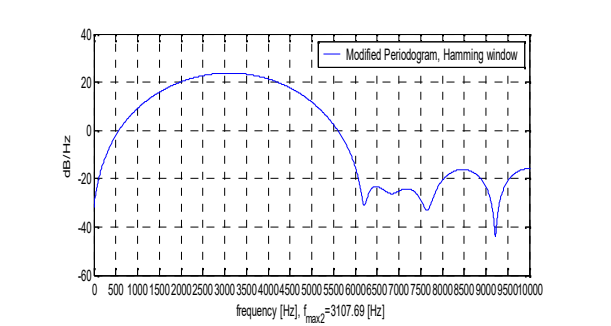
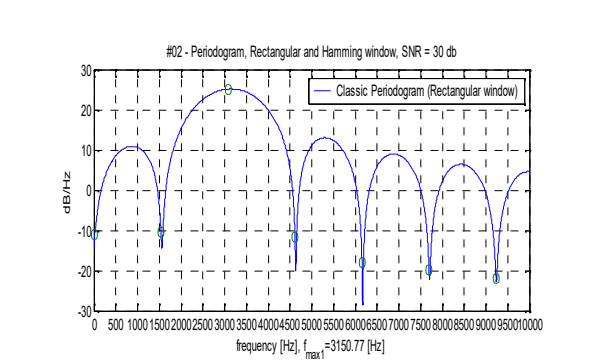
$$,\quad 0\leq n\leq N-1,$$

$$0\leq p\leq P-1,\quad D$$

$$0\leq n\leq D-1,\quad DP\leq N,$$

$$x^{(p)}[n]=x[pD+n].$$

$$x^{(p)}[n],\quad 0\leq p\leq P-1,$$



3.

$$.$$

$$\tilde{P}_{xx}^{(p)}(f)=\frac{1}{DT}\left|T\sum_{m=0}^{D-1}x^{(p)}[m]e^{-j2\pi fmT}\right|^2,$$

$$-\frac{1}{2T}\leq f\leq\frac{1}{2T},\quad (10)$$

$$f_k=k/KT,\quad 0\leq k\leq K-1.$$

$$f_i,$$

$$,$$

$$:$$

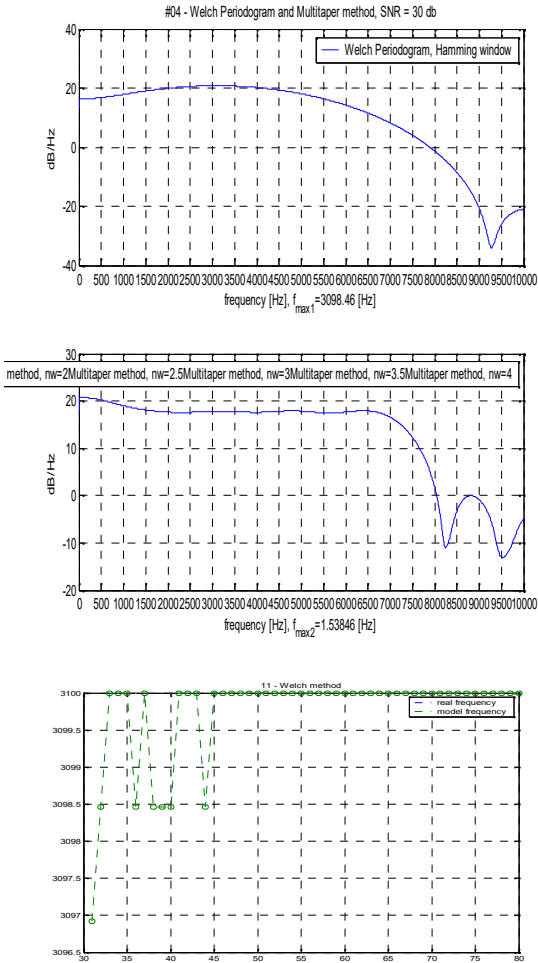
$$\mathcal{D}_B(f)=\frac{1}{P}\sum_{p=0}^{P-1}\tilde{P}_{xx}^{(p)}(f).$$

$$\mathcal{D}_B(f),\quad x^{(p)}[n]$$

$$,$$

$$:$$





. 4.

$MTM ($  )

,

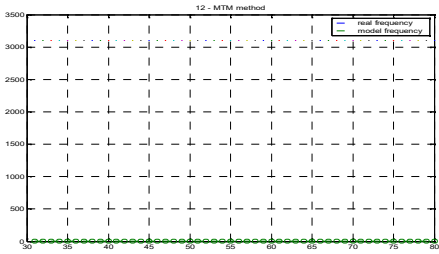
«
»
-
,
MATLAB
pmtm.
nw
-
nw = 4,
2, 5/2, 3, 7/2.
2nw-1.
method,
:
• adapt -
(
);
• unity -
1;
• eigen -
,
3000
,
:

(
).
{w\_k[n]},
0 ≤ k < K
,
pf\_N,
p/2 f\_N.
{w\_k[n]},
0 ≤ k < K,
2WNT : K < 2WNT,
2W, 2W > K/NT = Kf\_N, f\_N = 1 / NT,
W > Kf\_N/2 = K/2NT,
W ∈ [0; f\_N] ·
0 ≤ k < K,
X\_k^{(i)}(f) = ∑\_{n=1}^N w\_k[n]x\_i[n]e^{-j2πfnT},
D\_k^{(l,m)}(f) = 1/NT (X\_k^{(l)}(f))^\* (X\_k^{(m)}(f))
i=l i=m k {x\_i[n]}.

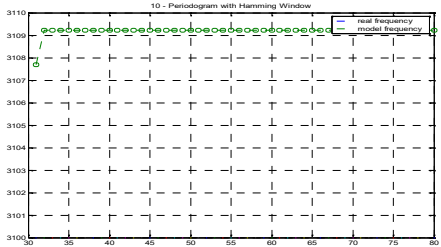
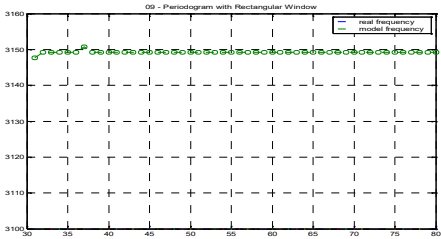
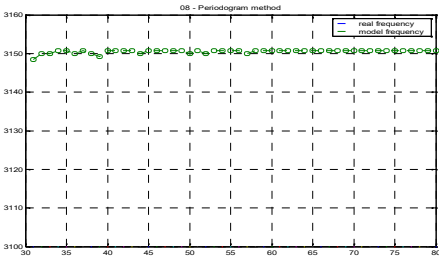
D\_{MTM}^{(l,m)}(f) = 1/K ∑\_{k=0}^{K-1} D\_k^{(l,m)}(f) ·
i=l=m

D\_{MTM}(f) = 1/K ∑\_{k=0}^{K-1} D\_k^{(i,i)}(f) ·

```
randn('state',0); fs = 1000; t = 0:1/fs:0.3;
x = cos(2*pi*t*300) + 0.1*randn(size(t));
[Pxx,Pxxc,f] = pmtm(x,3.5,512,fs,0.99);
hpsd = dspdata.psd([Pxx Pxxc],Fs',fs); plot(hpsd)
```



. 5.



. 6.



